

Probabilistic (Logic) Programming and its Applications

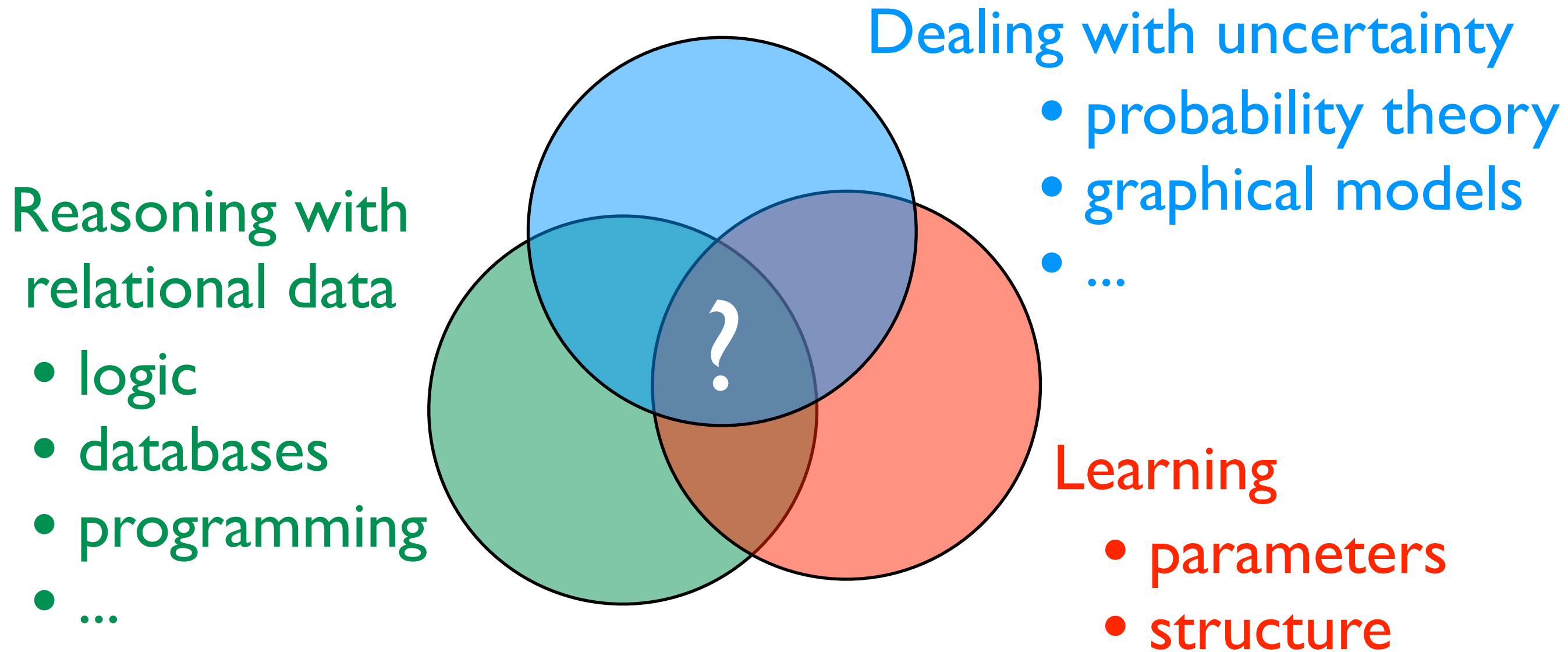
Luc De Raedt

with many slides from Angelika Kimmig



KU LEUVEN

A key question in AI:



Statistical relational learning
& Probabilistic Programming

The need for relations

Dynamics: Evolving Networks



- *Travian*: A massively multiplayer real-time strategy game
 - Commercial game run by TravianGames GmbH
 - ~3.000.000 players spread over different “worlds”
 - ~25.000 players in one world

[Thon et al. ECML 08]



World Dynamics

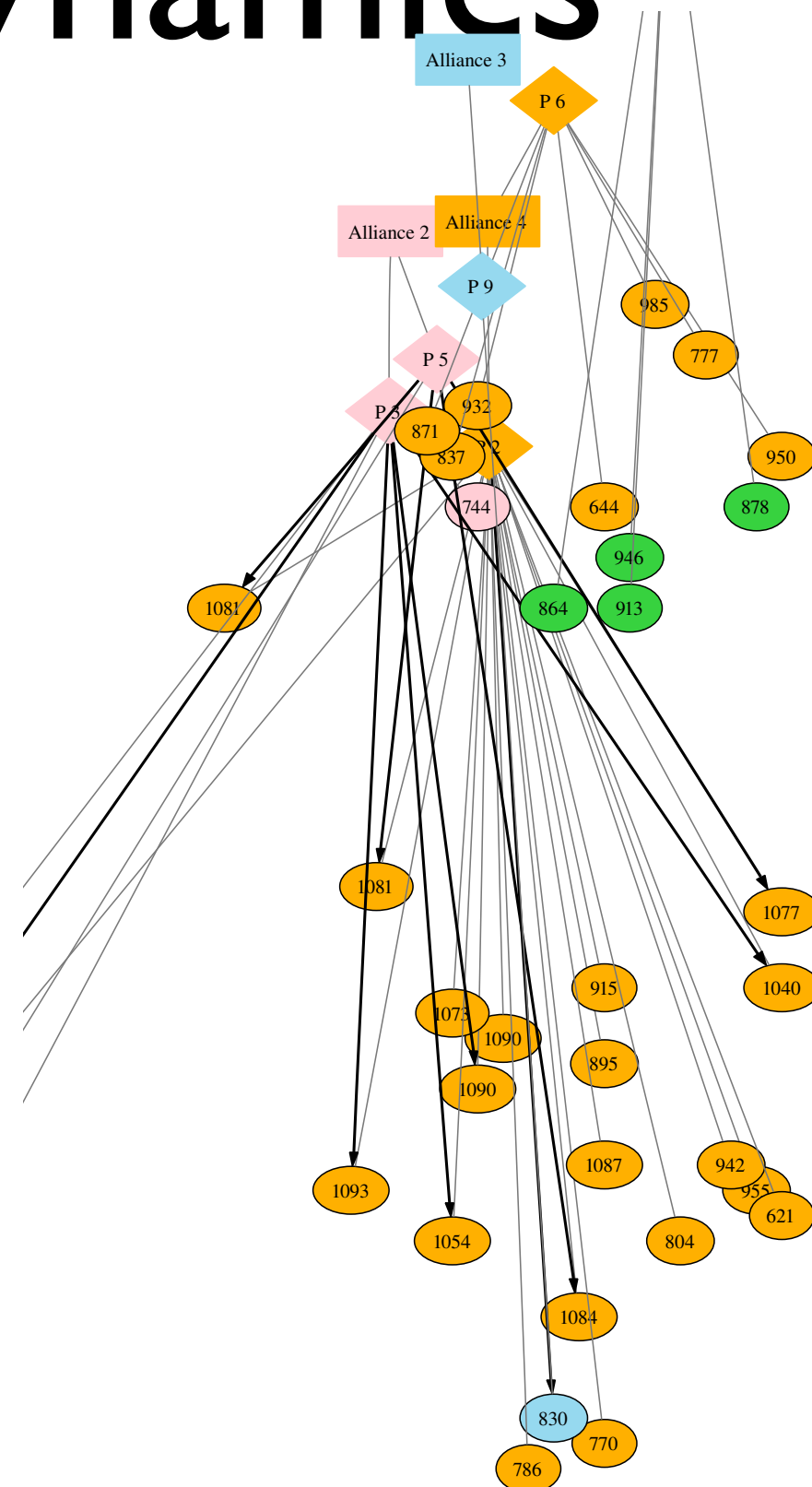
Fragment of world with

~10 alliances
~200 players
~600 cities

alliances color-coded

Can we build a model
of this world ?
Can we use it for playing
better ?

[Thon, Landwehr, De Raedt, ECML08]



World Dynamics

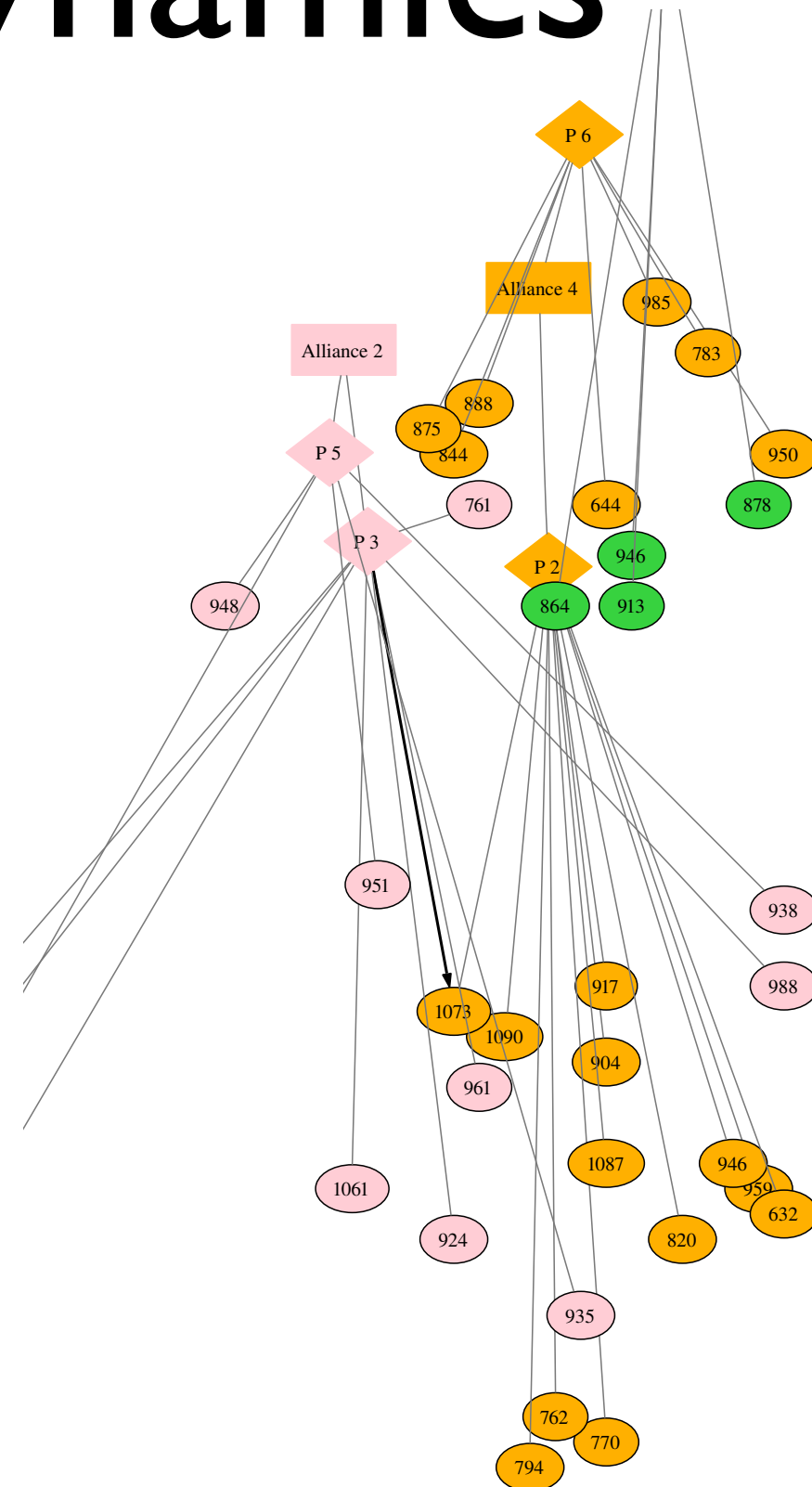
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World Dynamics

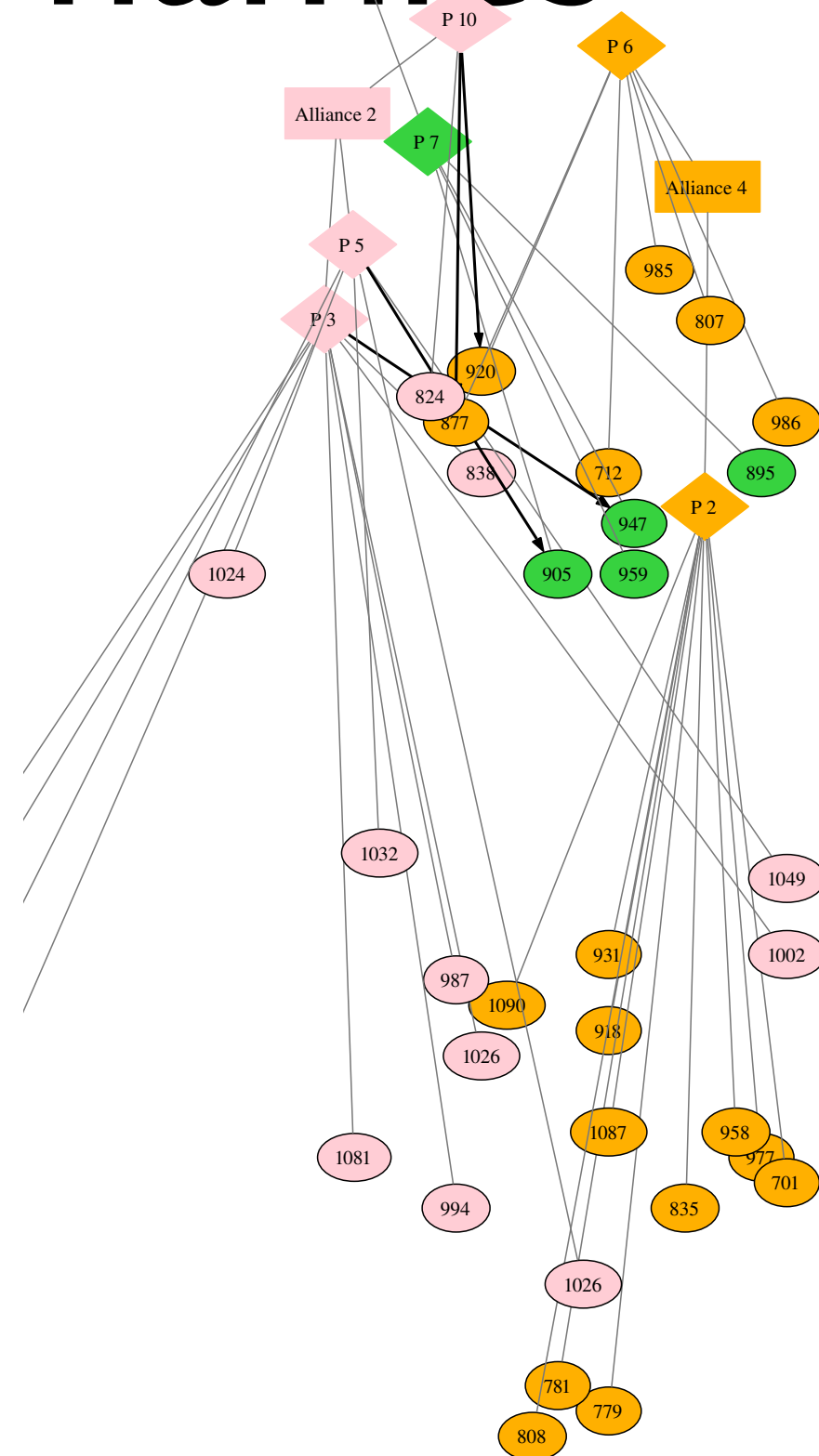
Fragment of world with

- ~10 alliances
- ~200 players
- ~600 cities

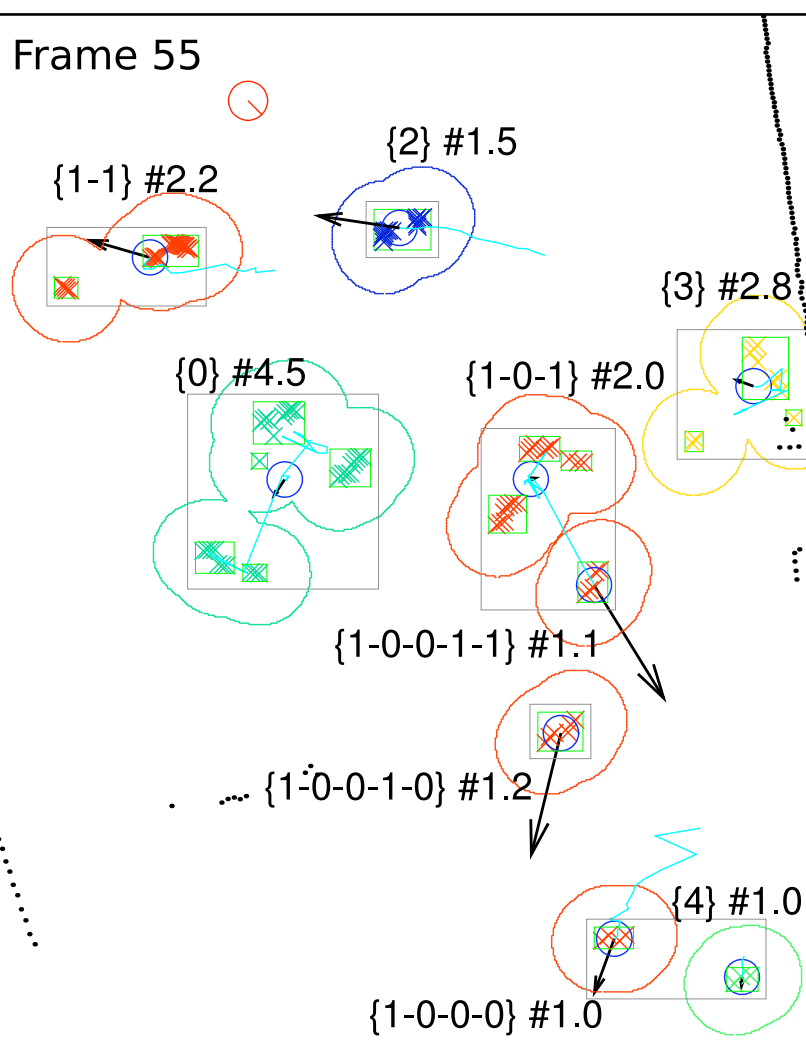
alliances color-coded

Can we build a model
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Can we use it for playing
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[Thon, Landwehr, De Raedt, ECML08]



Analyzing Video Data



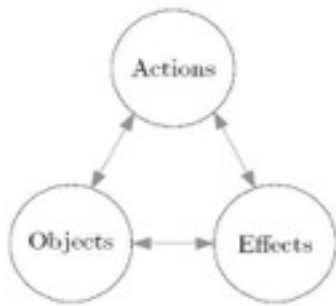
- Track people or objects over time? Even if temporarily hidden?

[Skarlatidis et al, TPLP 14;
Nitti et al, IROS 13, ICRA 14]

- Recognize activities?
- Infer object properties?

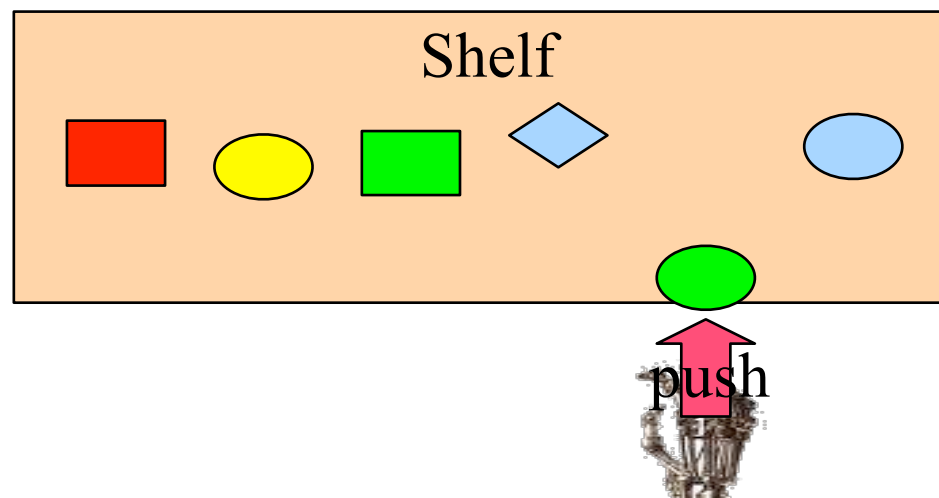
Learning relational affordances

Learn probabilistic model



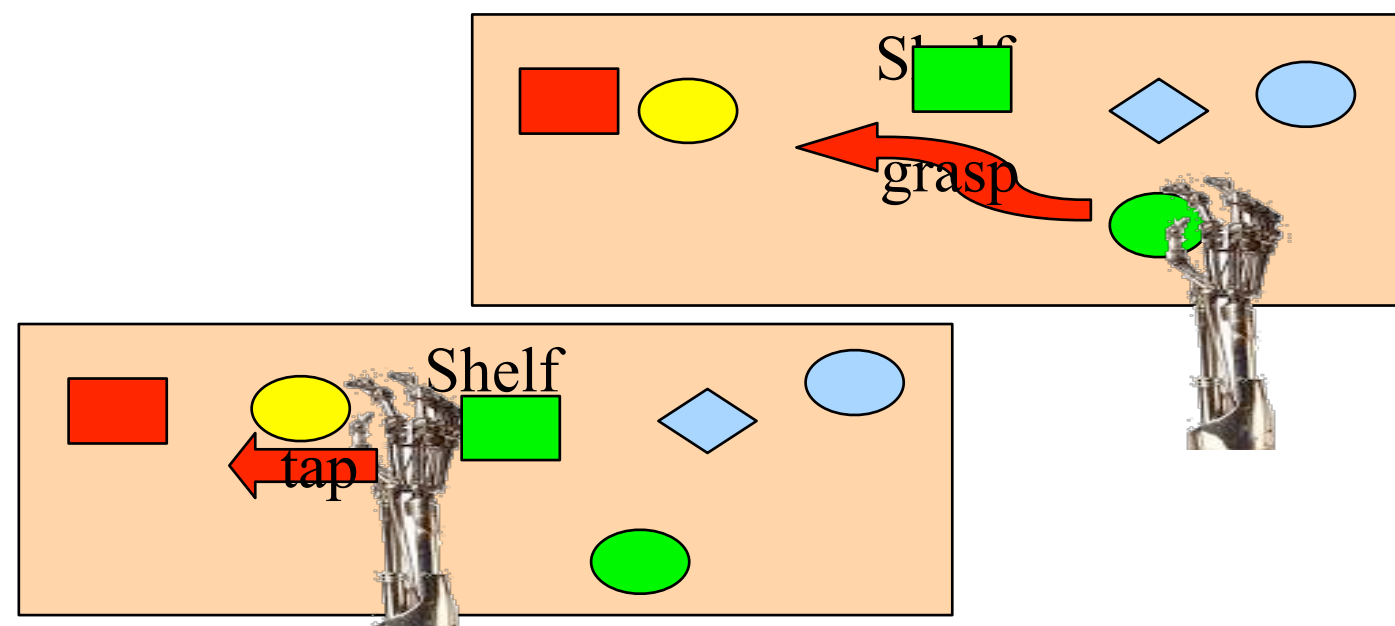
Inputs	Outputs	Function
(O, A)	E	Effect prediction
(O, E)	A	Action recognition/planning
(A, E)	O	Object recognition/selection

From two object interactions
Generalize to N
























Learning relational
affordances
between
two objects
(learnt by experience)

Moldovan et al. ICRA 12, 13, 14, PhD 15



Example: Information Extraction

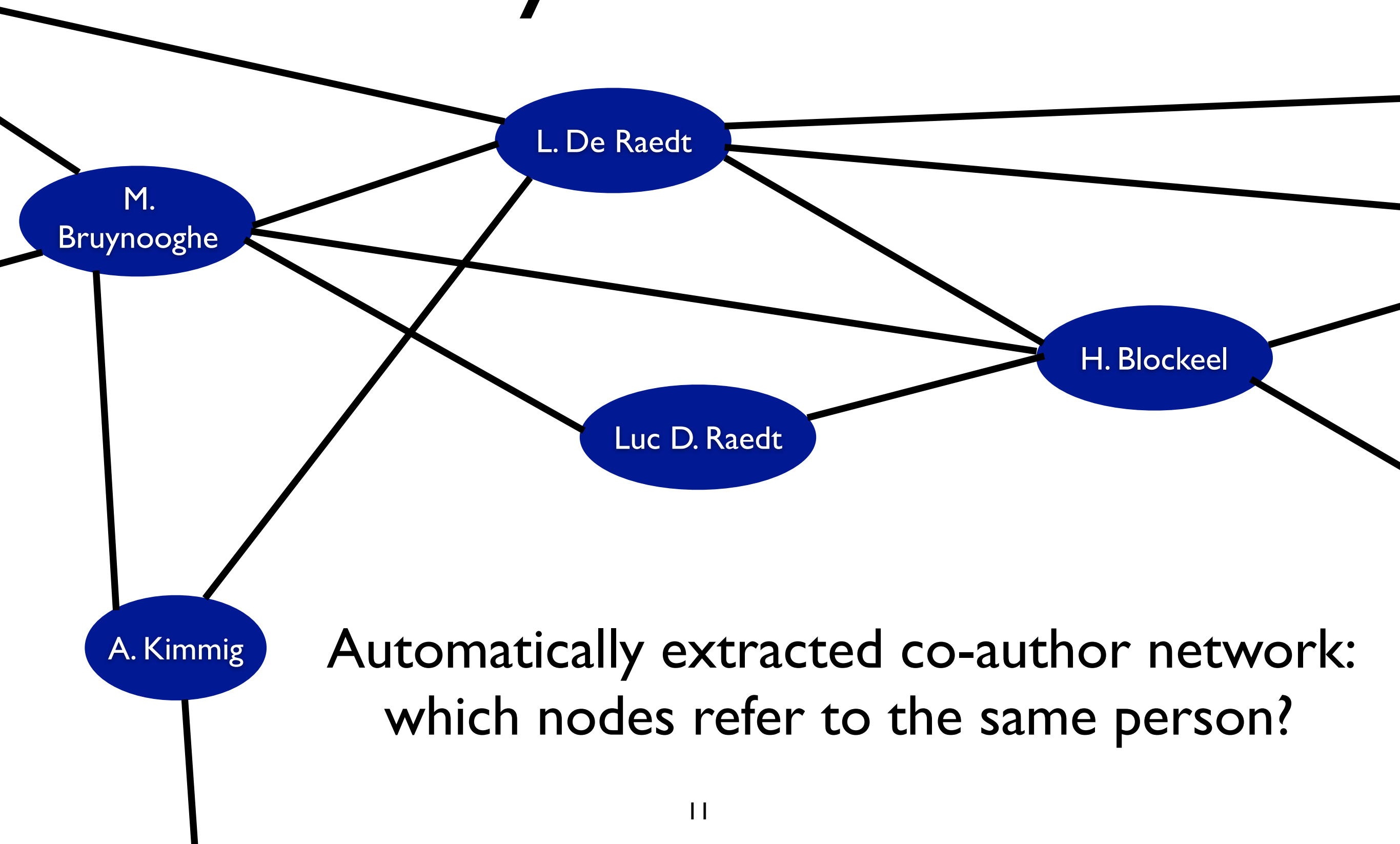
Recently-Learned Facts 

instance	iteration	date learned	confidence
<u>kelly andrews</u> is a <u>female</u>	826	29-mar-2014	98.7  
<u>investment next year</u> is an <u>economic sector</u>	829	10-apr-2014	95.3  
<u>shibenik</u> is a <u>geopolitical entity</u> that is an organization	829	10-apr-2014	97.2  
<u>quality web design work</u> is a <u>character trait</u>	826	29-mar-2014	91.0  
<u>mercedes benz cls by carlsson</u> is an <u>automobile manufacturer</u>	829	10-apr-2014	95.2  
<u>social work</u> is an academic program <u>at the university rutgers university</u>	827	02-apr-2014	93.8  
<u>dante wrote</u> the book <u>the divine comedy</u>	826	29-mar-2014	93.8  
<u>willie aames</u> was <u>born in</u> the city <u>los angeles</u>	831	16-apr-2014	100.0  
<u>kitt peak</u> is a mountain <u>in the state or province arizona</u>	831	16-apr-2014	96.9  
<u>greenwich</u> is a park <u>in the city london</u>	831	16-apr-2014	100.0  

↑
instances for many
different relations

↑
degree of certainty

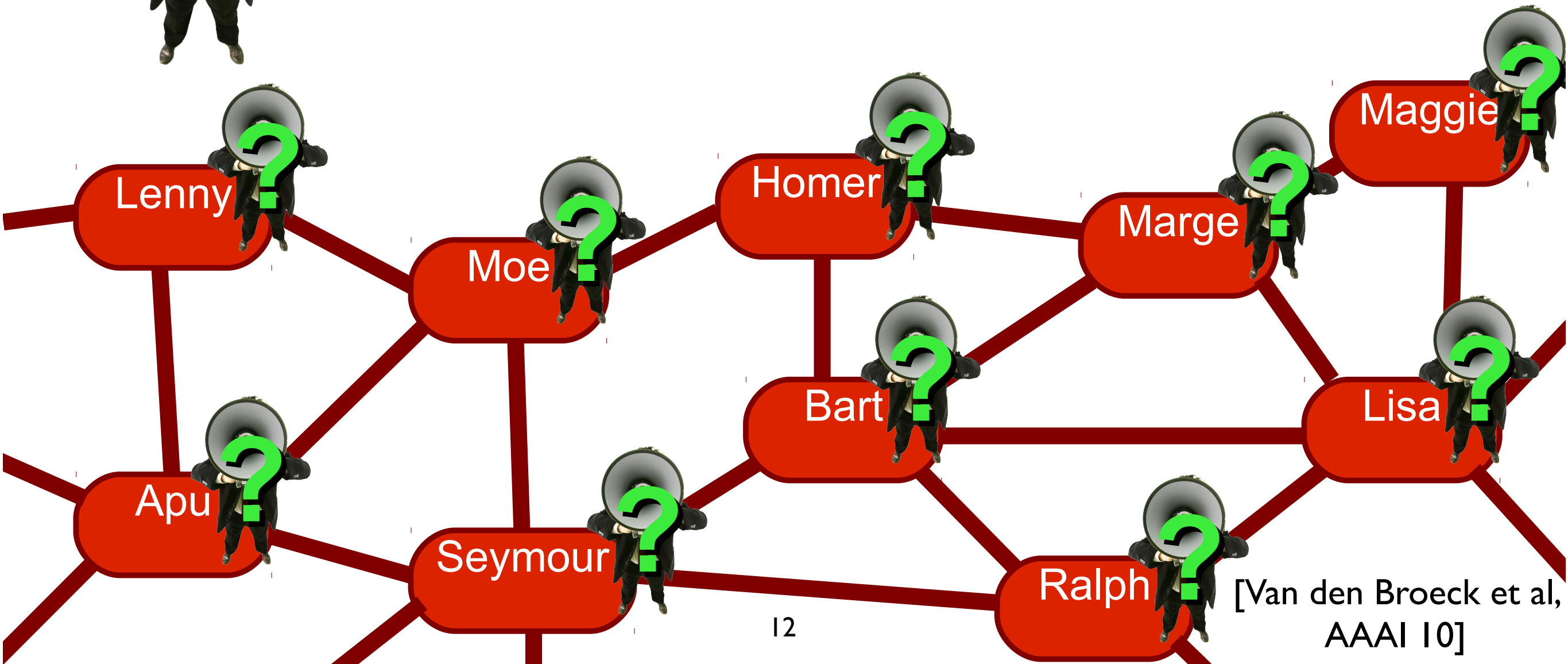
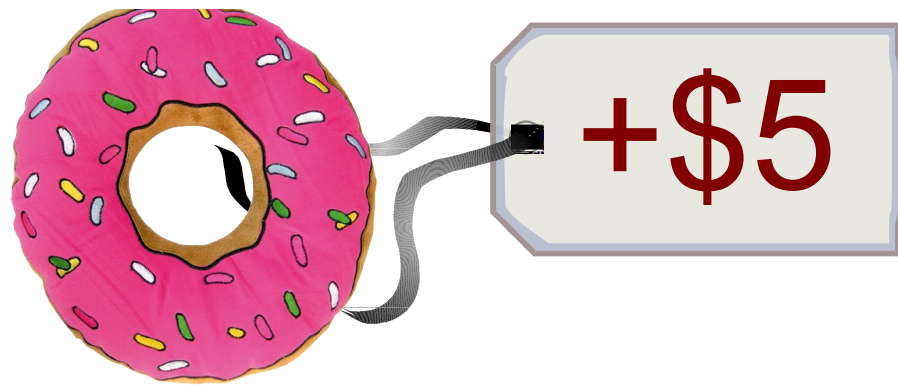
Entity Resolution



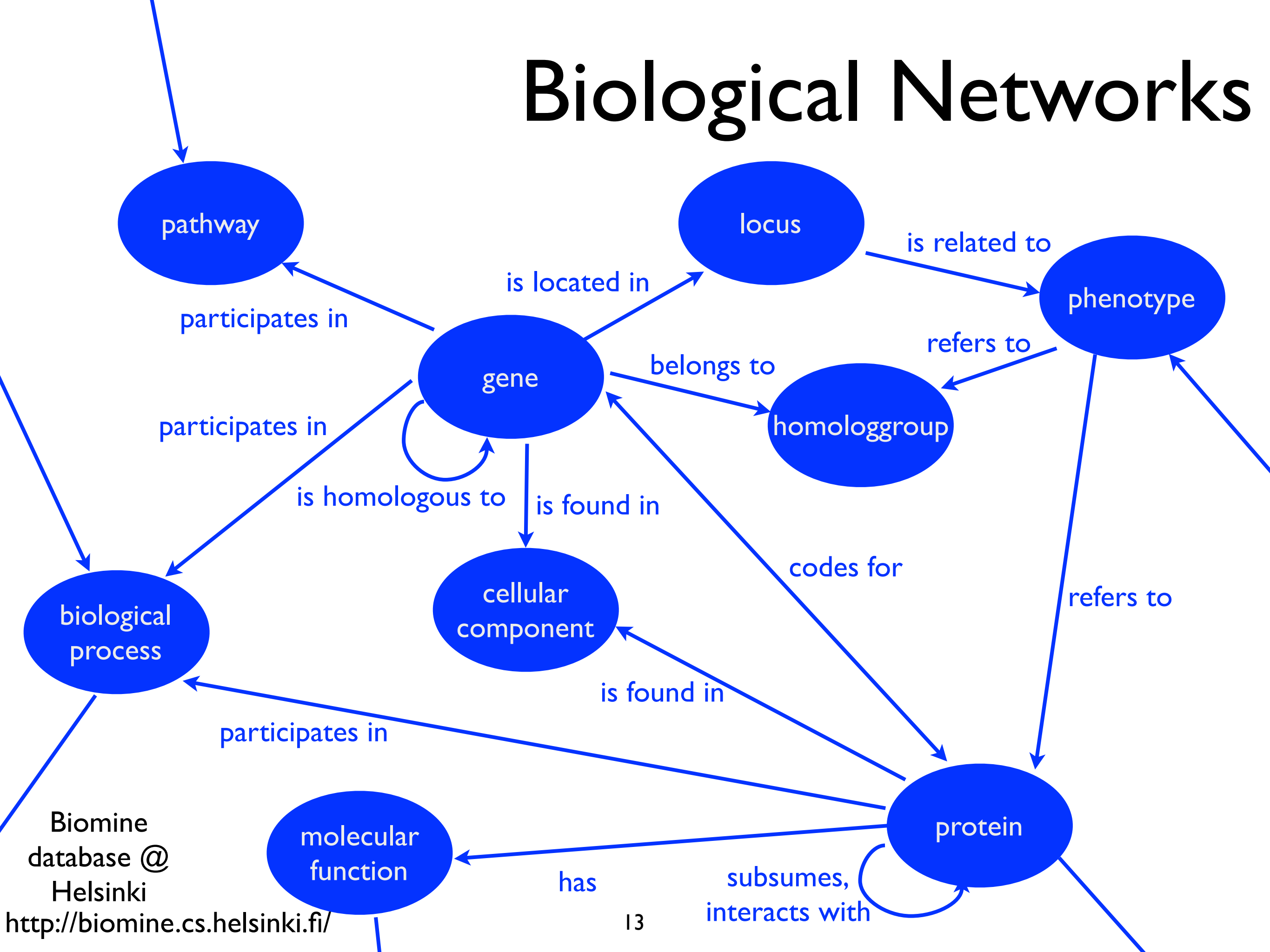
Automatically extracted co-author network:
which nodes refer to the same person?

Viral Marketing

Which advertising strategy maximizes expected profit?



Biological Networks

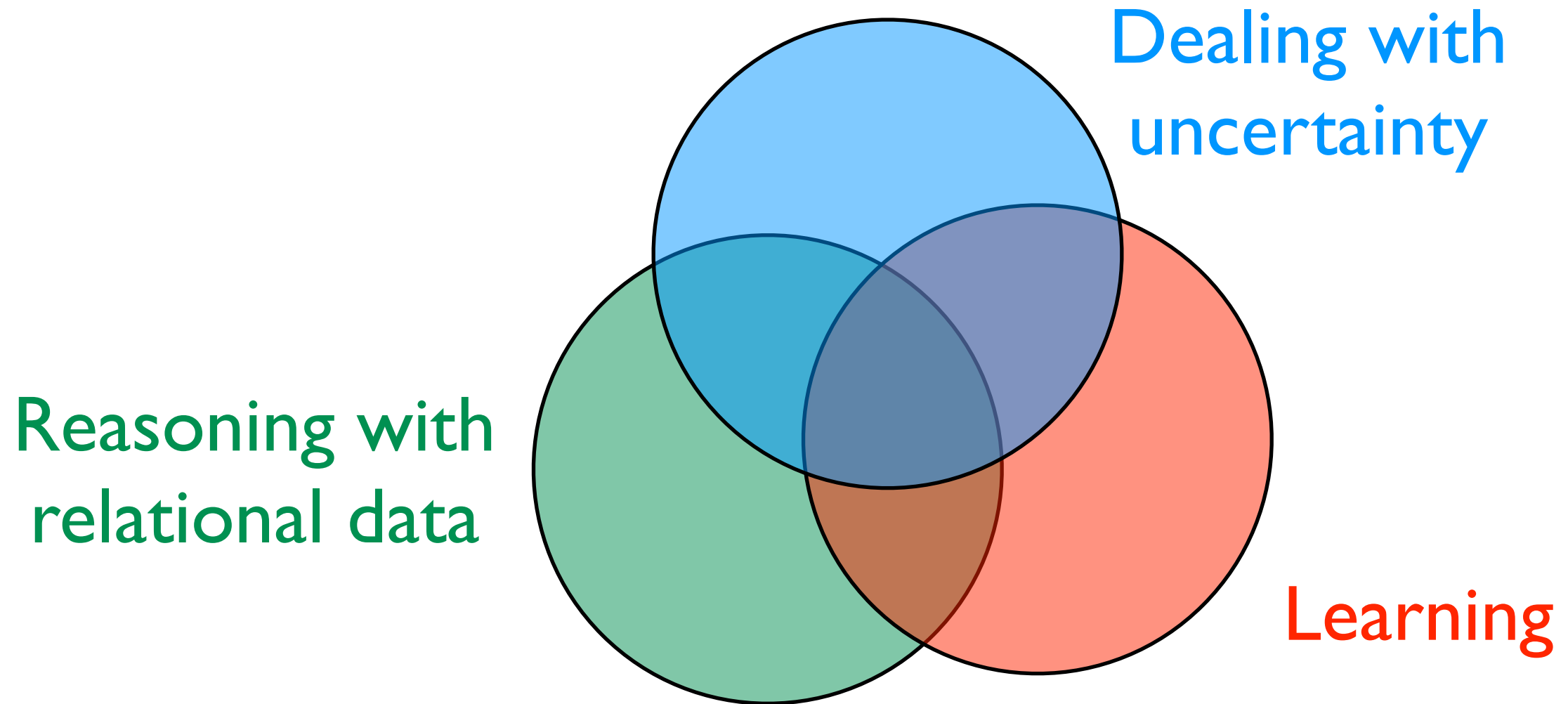


This requires dealing with

- Structured environments
 - objects, and
 - **relationships** amongst them
- and possibly
 - using background knowledge
- cope with **uncertainty**
- **learn from data**

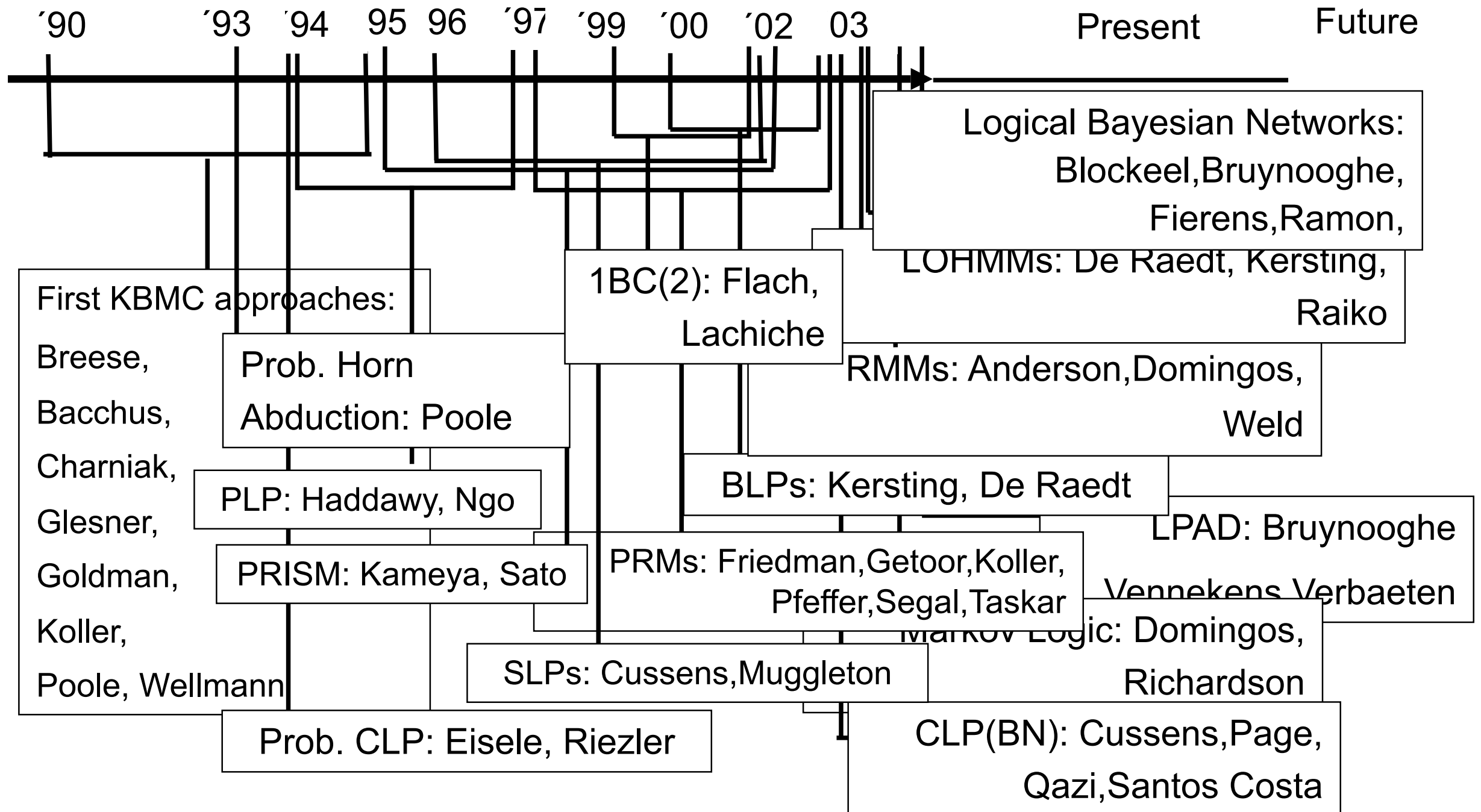
Statistical Relational Learning
Probabilistic Programming

Common theme

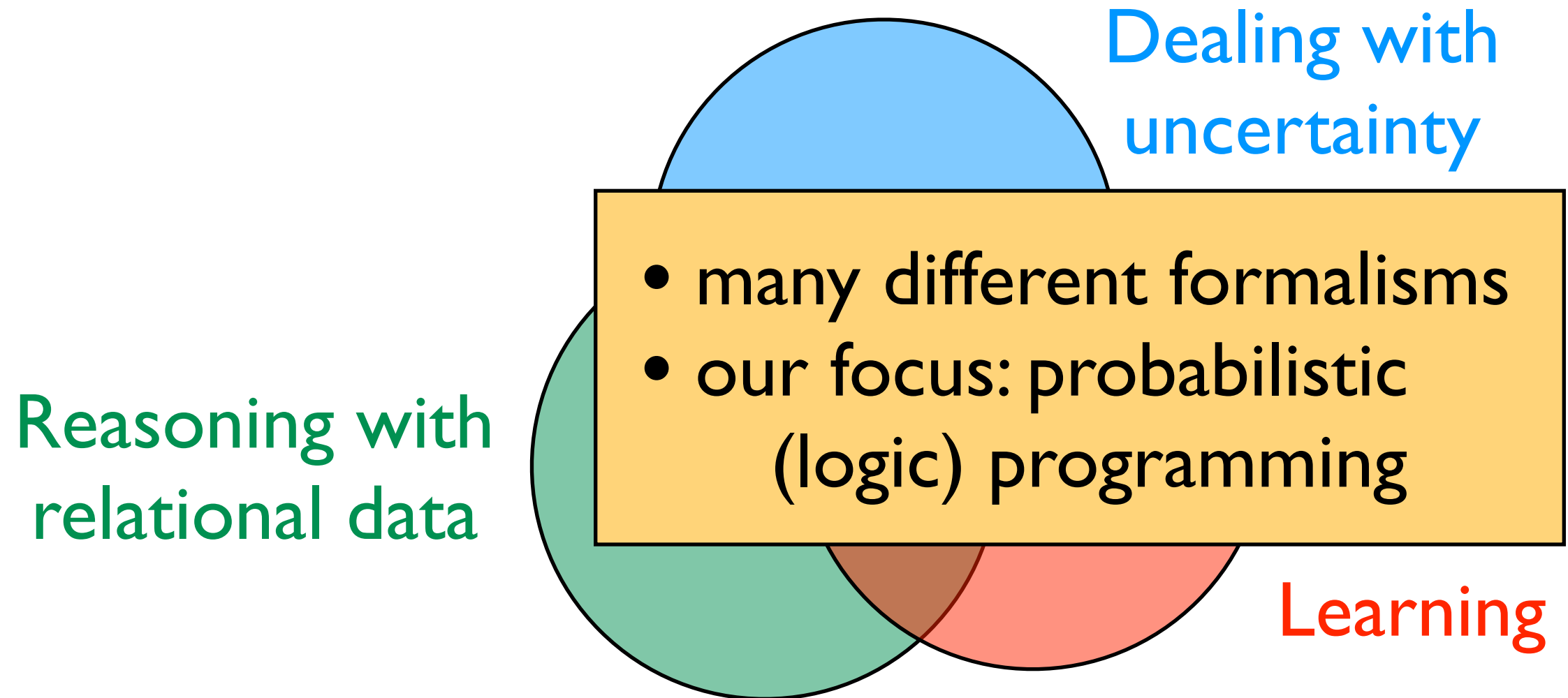


Statistical relational learning
& Probabilistic Programming, ...

Some formalisms



Common theme



Statistical relational learning
& Probabilistic Programming, ...

ProbLog

probabilistic Prolog

several possible worlds

```
0.8::stress(ann).  
0.6::influences(ann,bob).  
0.2::influences(bob,carl).
```

atoms as random
variables
Dealing with
uncertainty

Reasoning with
probabilistic
programs

```
stress(ann).  
influences(ann,bob).  
influences(bob,carl).
```

```
smokes(X) :- stress(X).  
smokes(X) :-  
    influences(Y,X), smokes(Y).
```

one world

Learning
parameter learning,
adapted relational
learning techniques

Probabilistic Logic Programming

Distribution Semantics [Sato, ICLP 95]:
probabilistic choices + logic program
→ distribution over possible worlds

e.g., PRISM, ICL, ProbLog, LPADs, CP-logic, ...

multi-valued
switches

probabilistic
facts

probabilistic
alternatives

annotated
disjunctions

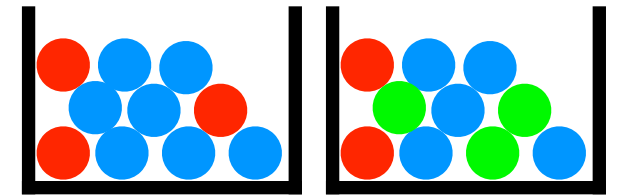
causal-
probabilistic
laws

Roadmap

- Modeling (ProbLog and Church, another representative of PP)
- Inference
- Learning
- Dynamics and Decisions

... with some detours on the way

ProbLog by example:



A bit of gambling

- toss (biased) coin & draw ball from each urn
- win if (heads and a red ball) or (two balls of same color)

```
0.4 :: heads.
```

probabilistic fact: heads is true with probability 0.4 and false with 0.6)
annotated disjunction: first ball is red with probability 0.3 and blue with 0.7

```
0.3 :: col(1,red) ; 0.7 :: col(1,blue) .
```

```
0.2 :: col(2,red) ; 0.3 :: col(2,green) ;
```

```
0.5 :: col(2,blue) .
```

annotated disjunction: second ball is red with probability 0.2, green with 0.3, and blue with 0.5

```
win :- heads, col(1,red) .  
win :- col(1,C) , col(2,C) .
```

logical rule encoding background knowledge
consequences

Questions

0.4 :: heads.

0.3 :: col(1,red) ; 0.7 :: col(1,blue).

0.2 :: col(2,red) ; 0.3 :: col(2,green) ; 0.5 :: col(2,blue).

win :- heads, col(_,red).

win :- col(1,C), col(2,C).

marginal probability

- Probability of **win**

query

conditional probability

- Probability of **win** given **col(2,green)**?

evidence

- Most probable world where **win** is true?

MPE inference

Possible Worlds

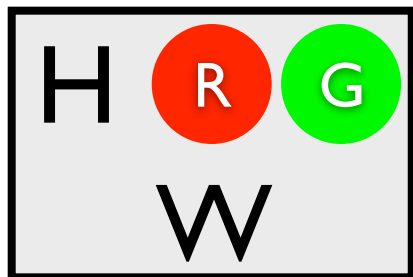
```
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```

```
0.3 :: col(1,red); 0.7 :: col(1,blue)
```

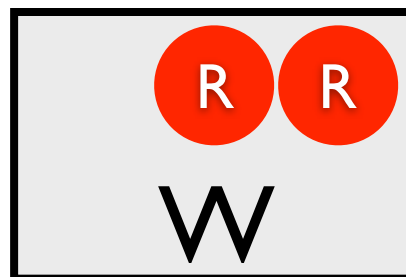
```
0.2 :: col(2,red); 0.3 :: col(2,green); 0.5 :: col(2,blue).
```

```
win :- heads, col(_,red).  
win :- col(1,C), col(2,C).
```

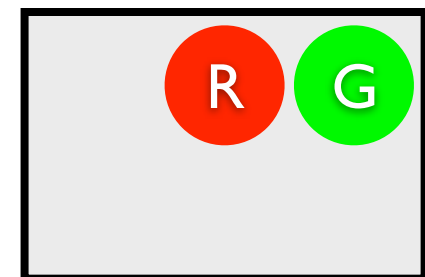
$$0.4 \times 0.3 \times 0.3$$



$$(1-0.4) \times 0.3 \times 0.2$$

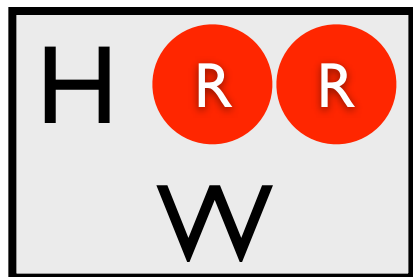


$$(1-0.4) \times 0.3 \times 0.3$$

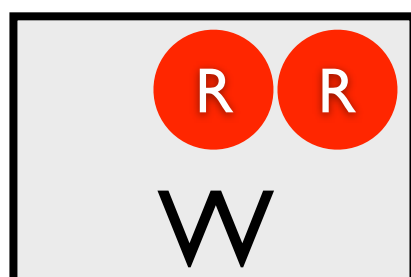


All Possible Worlds

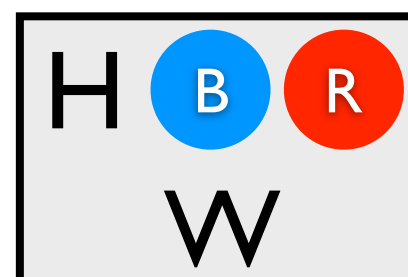
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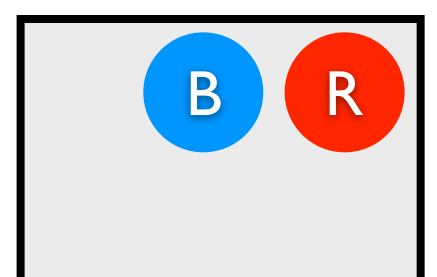
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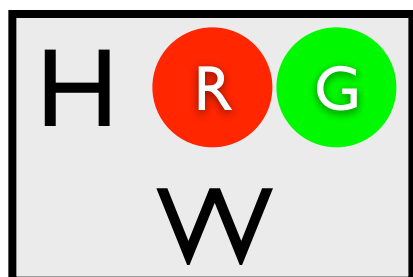
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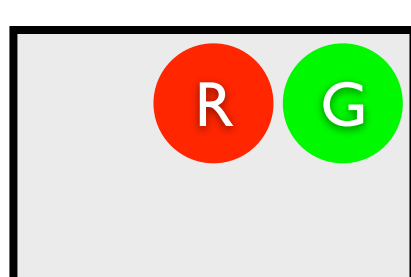
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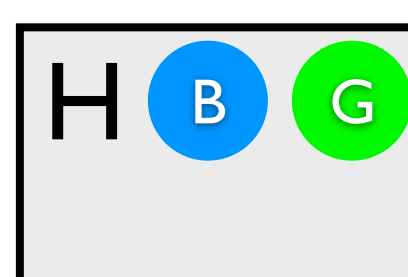
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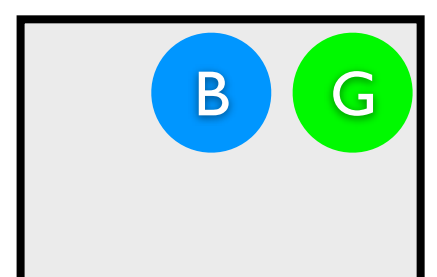
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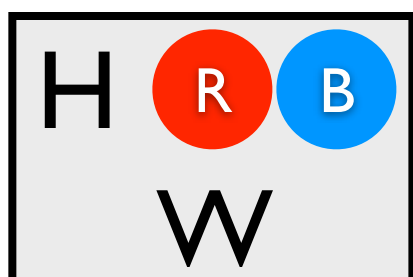
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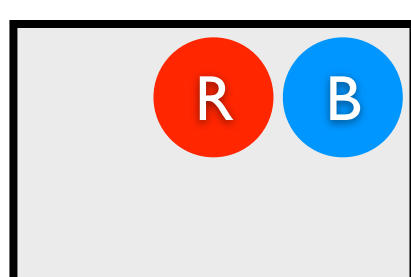
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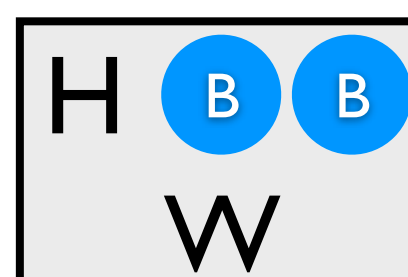
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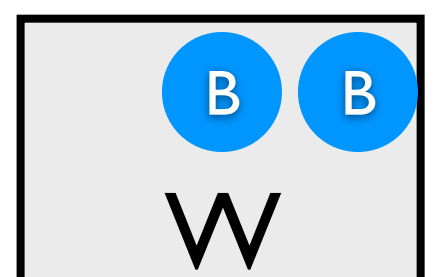
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0.140



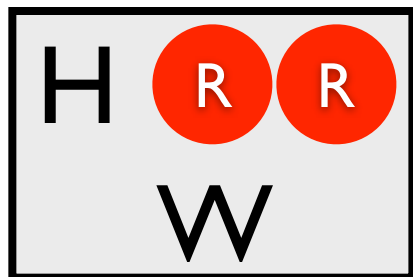
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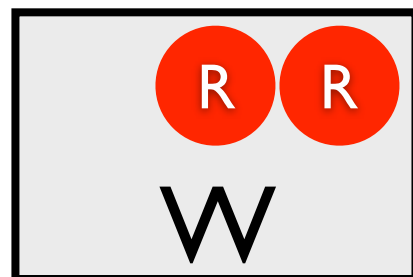
Most likely world where `win` is true?

MPE Inference

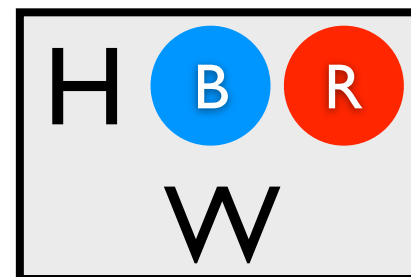
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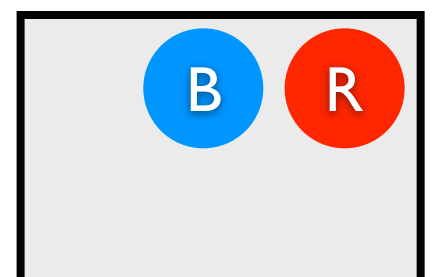
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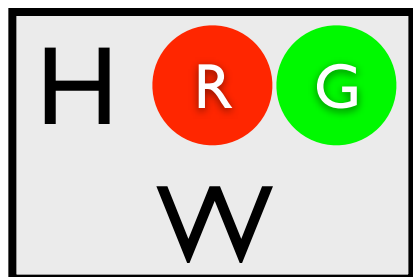
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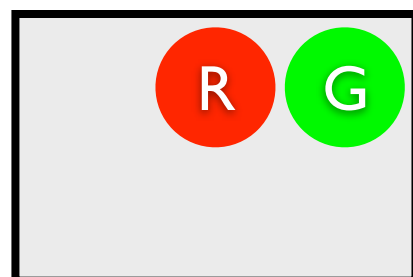
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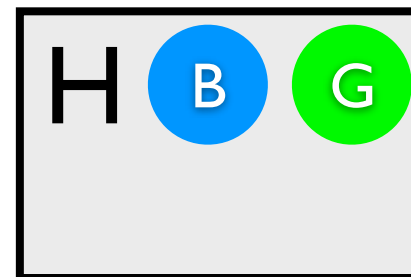
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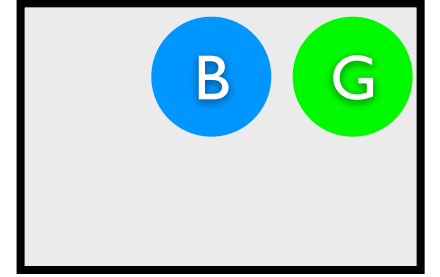
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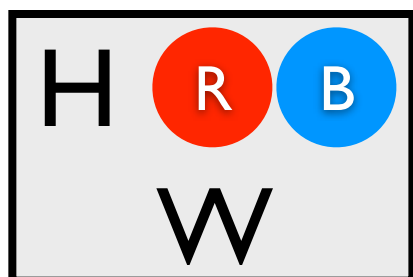
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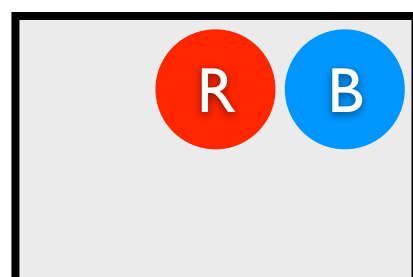
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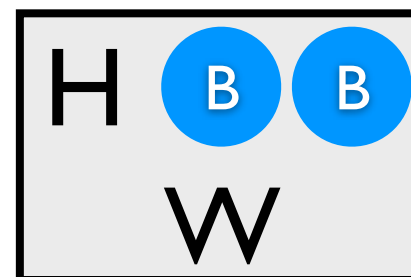
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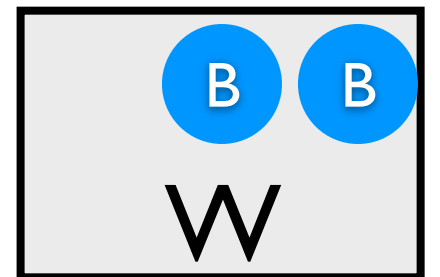
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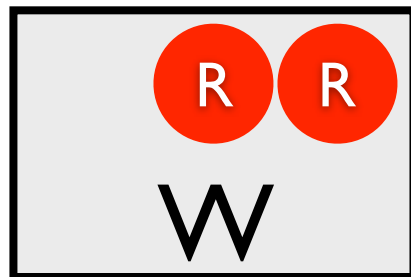
Most likely world where `col(2, blue)` is false?

MPE Inference

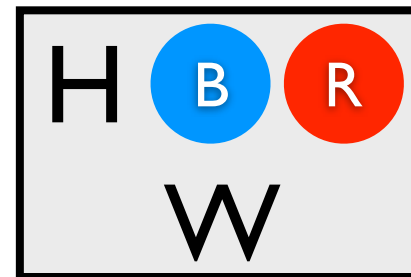
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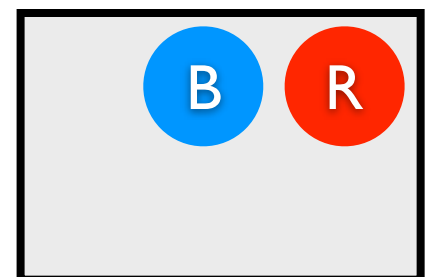
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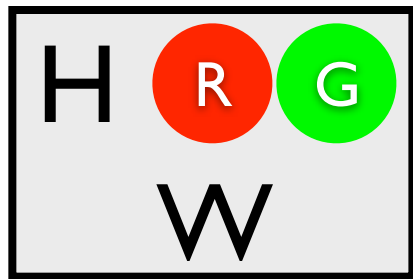
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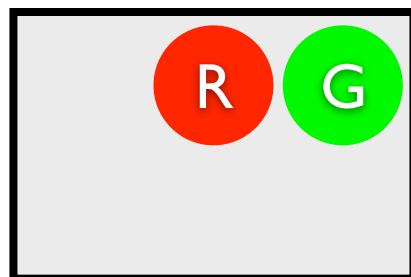
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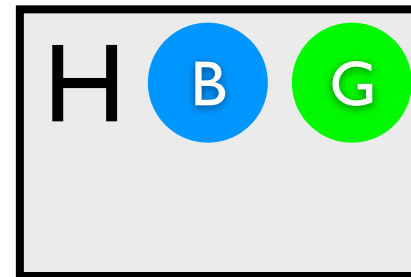
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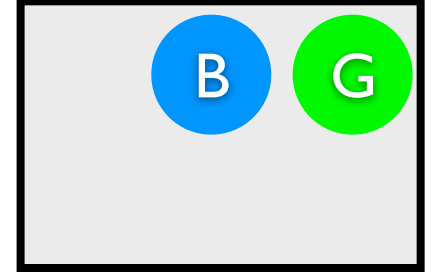
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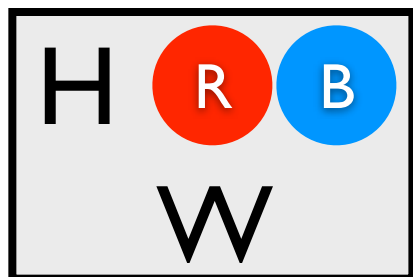
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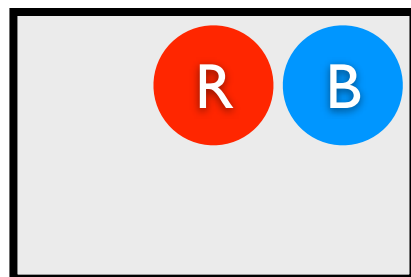
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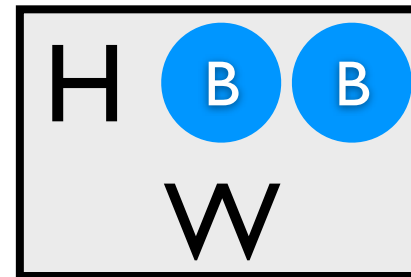
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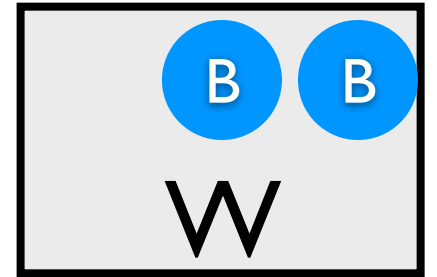
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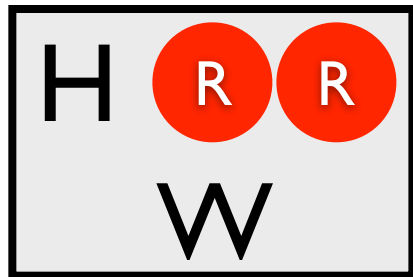
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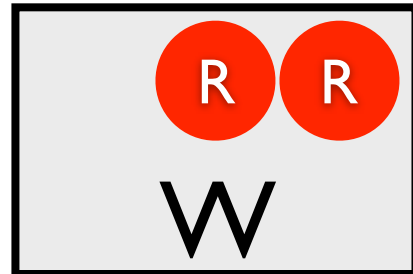
$$P(\text{win}) = \sum = 0.562$$

Marginal
Probability

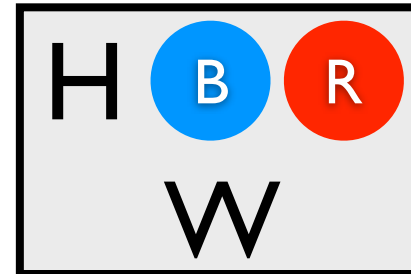
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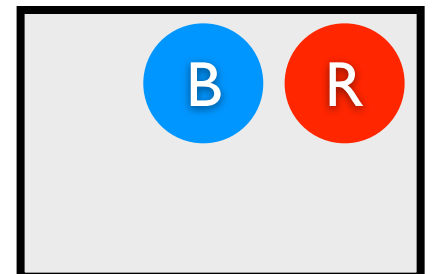
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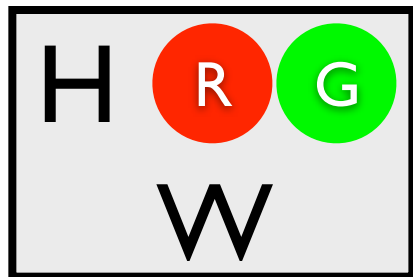
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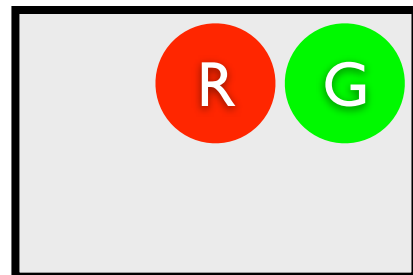
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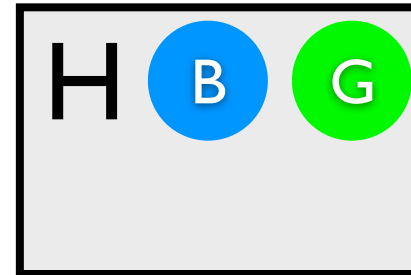
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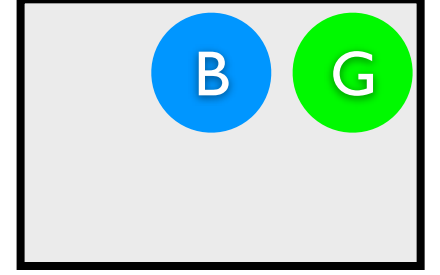
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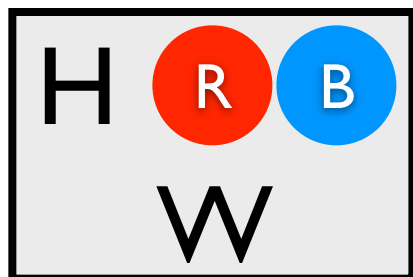
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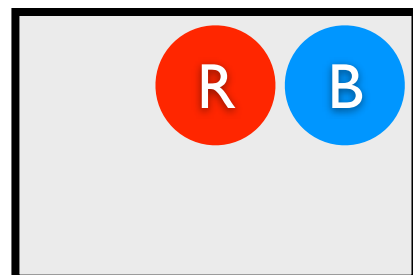
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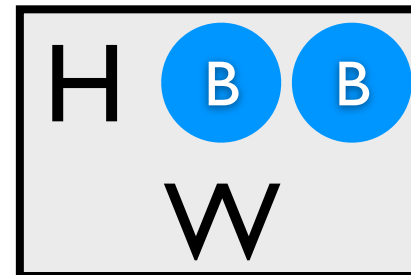
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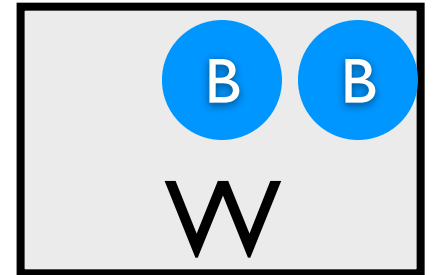
0.090



0.140



0.210



$$P(\text{win} | \text{col}(2, \text{green})) = ? / \Sigma$$

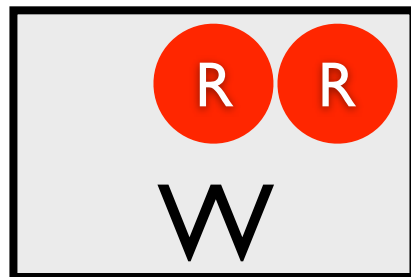
$$= P(\text{win} \wedge \text{col}(2, \text{green}) = 0.036 / P(\text{col}(2, \text{green}) = 0.3)$$

Conditional
Probability

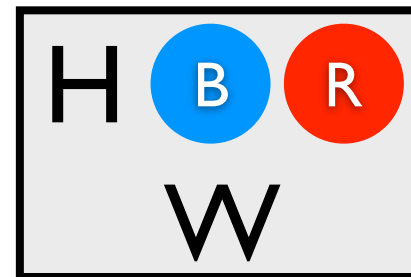
0.024



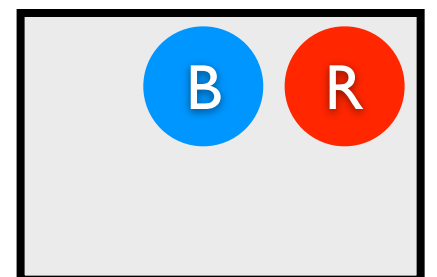
0.036



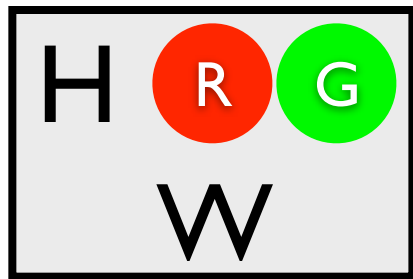
0.056



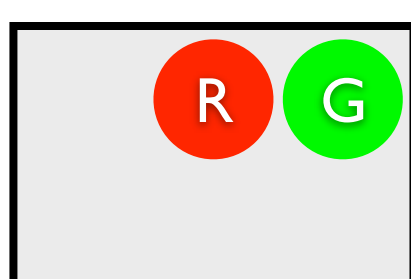
0.084



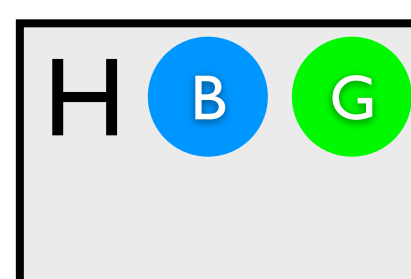
0.036



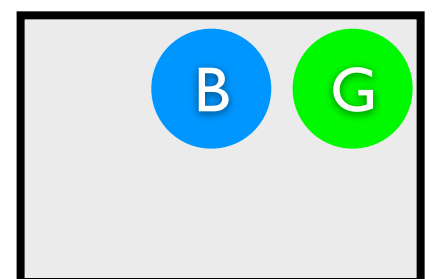
0.054



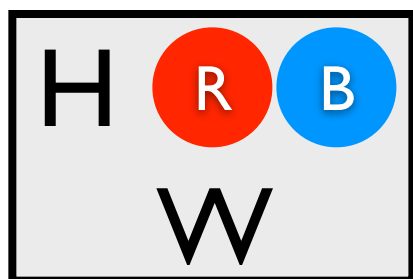
0.084



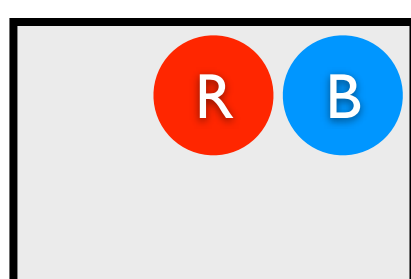
0.126



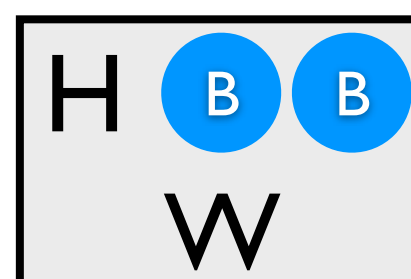
0.060



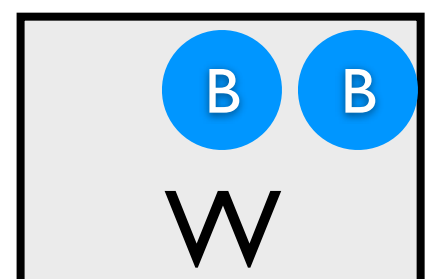
0.090



0.140



0.210

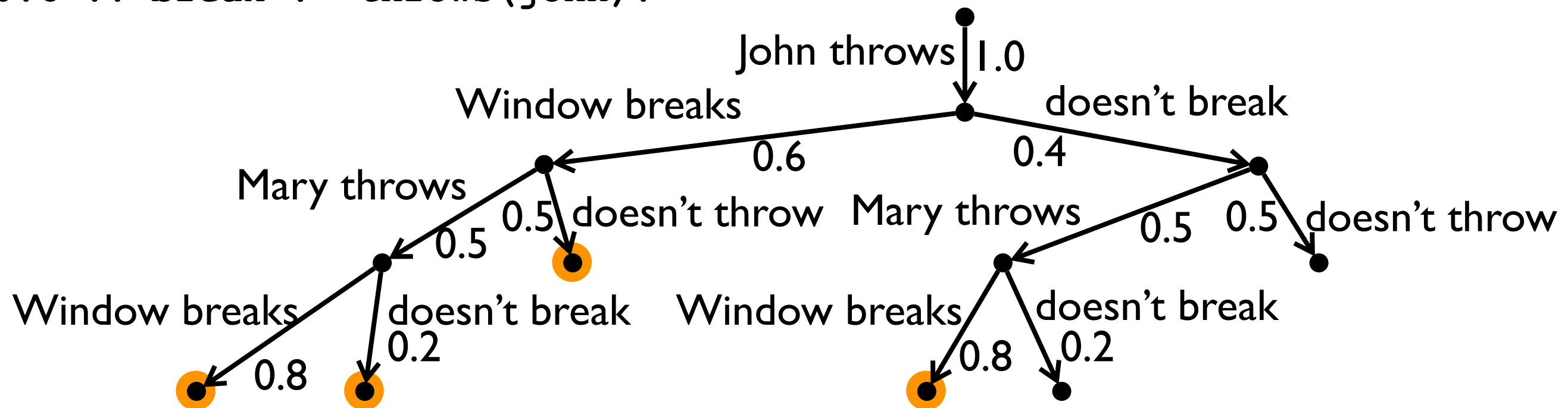


Alternative view: CP-Logic

```
throws(john) .
0.5 :: throws(mary) .
```

probabilistic causal laws

```
0.8 :: break :- throws(mary) .
0.6 :: break :- throws(john) .
```



$$P(\text{break}) = 0.6 \times 0.5 \times 0.8 + 0.6 \times 0.5 \times 0.2 + 0.6 \times 0.5 + 0.4 \times 0.5 \times 0.8$$

Distributional Clauses (DC)

Closely related to BLOG [Russell et al.]

- Discrete- and continuous-valued random variables

random variable with Gaussian distribution

```
length(Obj) ~ gaussian(6.0,0.45) :- type(Obj,glass).
```

```
stackable(Obj1,Obj2) :-
```

```
    ≈length(Obj1) ≥ ≈length(Obj2),
```

```
    ≈width(Obj1) ≥ ≈width(Obj2).
```

comparing values of
random variables

```
ontype(Obj,plate) ~ finite([0 : glass, 0.0024 : cup,  
                           0 : pitcher, 0.8676 : plate,  
                           0.0284 : bowl, 0 : serving,  
                           0.1016 : none])
```

```
:- obj(Obj), on(Obj,O2), type(O2,plate).
```

random variable with
discrete distribution



Distributional Clauses (DC)

- Defines a generative process (as for CP-logic)
- Logic programming variant of Blog
- Tree can become infinitely wide
 - Sampling
- Well-defined under reasonable assumptions

Probabilistic Databases

several possible worlds

bornIn		
person	city	P
ann	london	0,87
bob	york	0,95
		0,9
		0,56

cityIn		
city	country	P
london	uk	0,99
york	uk	0,75
paris	usa	0,4

probabilistic tables + database queries
→ distribution over possible worlds

tuple dealing with

uncertainty

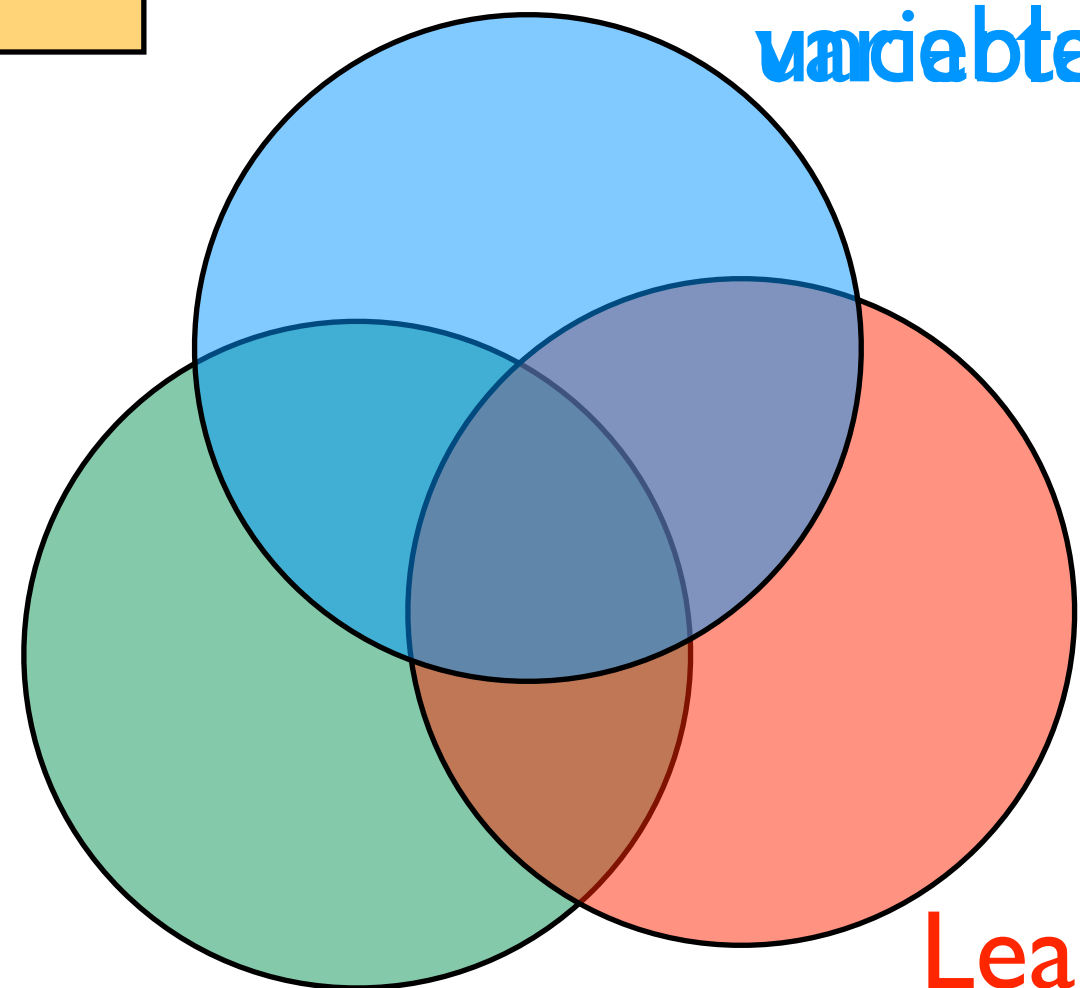
select
from bornIn x, cityIn y
where x.city=y.city

one world

bornIn	
person	city
ann	london
bob	york
eve	new york
tom	paris


cityIn	
city	country
london	uk
york	uk
paris	usa

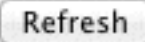
Reasoning with
relational data























Learning

Example: Information Extraction

Recently-Learned Facts 



instance	iteration	date learned	confidence
<u>kelly andrews</u> is a <u>female</u>	826	29-mar-2014	98.7  
<u>investment next year</u> is an <u>economic sector</u>	829	10-apr-2014	95.3  
<u>shibenik</u> is a <u>geopolitical entity</u> that is an organization	829	10-apr-2014	97.2  
<u>quality web design work</u> is a <u>character trait</u>	826	29-mar-2014	91.0  
<u>mercedes benz cls by carlsson</u> is an <u>automobile manufacturer</u>	829	10-apr-2014	95.2  
<u>social work</u> is an academic program <u>at the university rutgers university</u>	827	02-apr-2014	93.8  
<u>dante wrote</u> the book <u>the divine comedy</u>	826	29-mar-2014	93.8  
<u>willie aames</u> was <u>born in</u> the city <u>los angeles</u>	831	16-apr-2014	100.0  
<u>kitt peak</u> is a mountain <u>in the state or province arizona</u>	831	16-apr-2014	96.9  
<u>greenwich</u> is a park <u>in the city london</u>	831	16-apr-2014	100.0  

↑
instances for many
different relations

↑
degree of certainty

Distribution Semantics

- **probabilistic choices** + their **consequences**
- probability distribution over **possible worlds**
- how to efficiently answer **questions?**
 - most probable world (MPE inference)
 - probability of query (computing marginals)
 - probability of query given evidence

Summary: ProbLog Syntax

- input database: ground facts

```
person(bob) .
```

- probabilistic facts

```
0.5::stress(bob) .
```

- annotated disjunctions

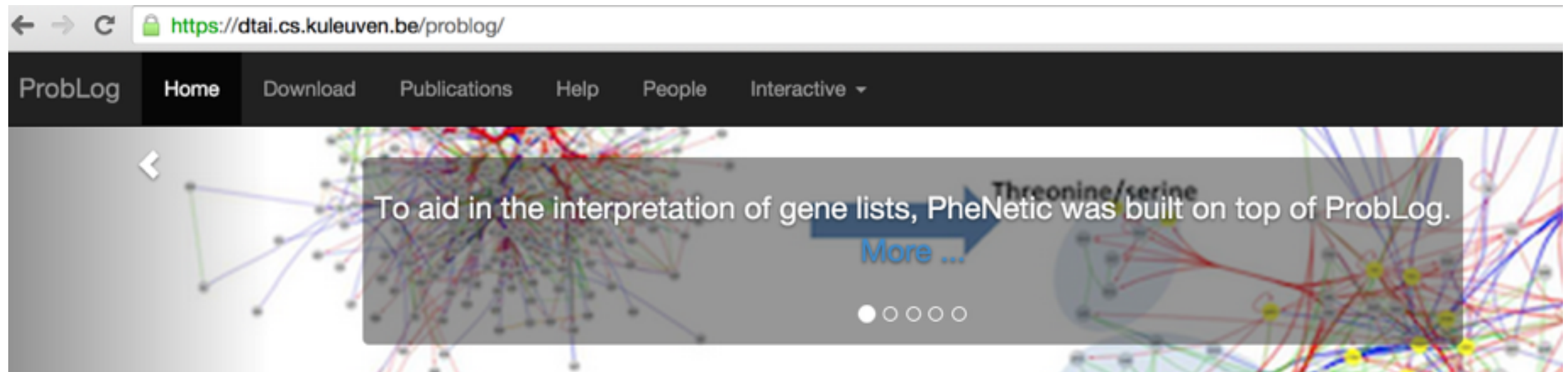
```
0.5::stress(X) :- person(X) .  
0.4::a(X) ; 0.3::b(X) ; 0.2::c(X) ; 0.1::d(X) :- q(X) .  
0.5::weather(sun,0) ; 0.5::weather(rain,0) .
```

- flexible probabilities

```
P::pack(Item) :- weight(Item,W), P is 1.0/W.
```

- Prolog clauses

```
smokes(X) :- influences(Y,X), smokes(Y) .  
excess([I|R],Limit) :- \+pack(I), excess(R,Limit) .
```



Introduction.

Probabilistic logic programs are logic programs in which some of the facts are annotated with probabilities.

ProbLog is a tool that allows you to intuitively build programs that do not only encode **complex interactions** between a large sets of **heterogenous components** but **uncertainties** that are present in real-life situations.

The engine tackles several tasks such as computing the marginals given evidence and learning from (partial) interpretations. ProbLog is a suite of efficient algorithms tasks. It is based on a conversion of the program and the queries and evidence to a weighted Boolean formula. This allows us to reduce the inference tasks to well-s weighted model counting, which can be solved using state-of-the-art methods known from the graphical model and knowledge compilation literature.

The Language. Probabilistic Logic Programming.

ProbLog makes it easy to express complex, probabilistic models.

```
0.3::stress(X) :- person(X).
0.2::influences(X,Y) :- person(X), person(Y).

smokes(X) :- stress(X).
smokes(X) :- friend(X,Y), influences(Y,X), smokes(Y).
```

Some Probabilistic Programming Languages outside LP

- IBAL [Pfeffer 01]
- Figaro [Pfeffer 09]
- Church [Goodman et al 08]
- BLOG [Milch et al 05]
- Venture [Mansingha et al.]
- Anglican and Probabilistic-C [Wood et al].
- and many more appearing recently

Church

probabilistic functional
programming

[Goodman et al, UAI 08]

**several
possible
executions**

```
(define randplus5  
  (lambda (x) (if (flip 0.6)  
                  (+ x 5)  
                  x)))  
  
(map randplus5 '(1 2 3))
```

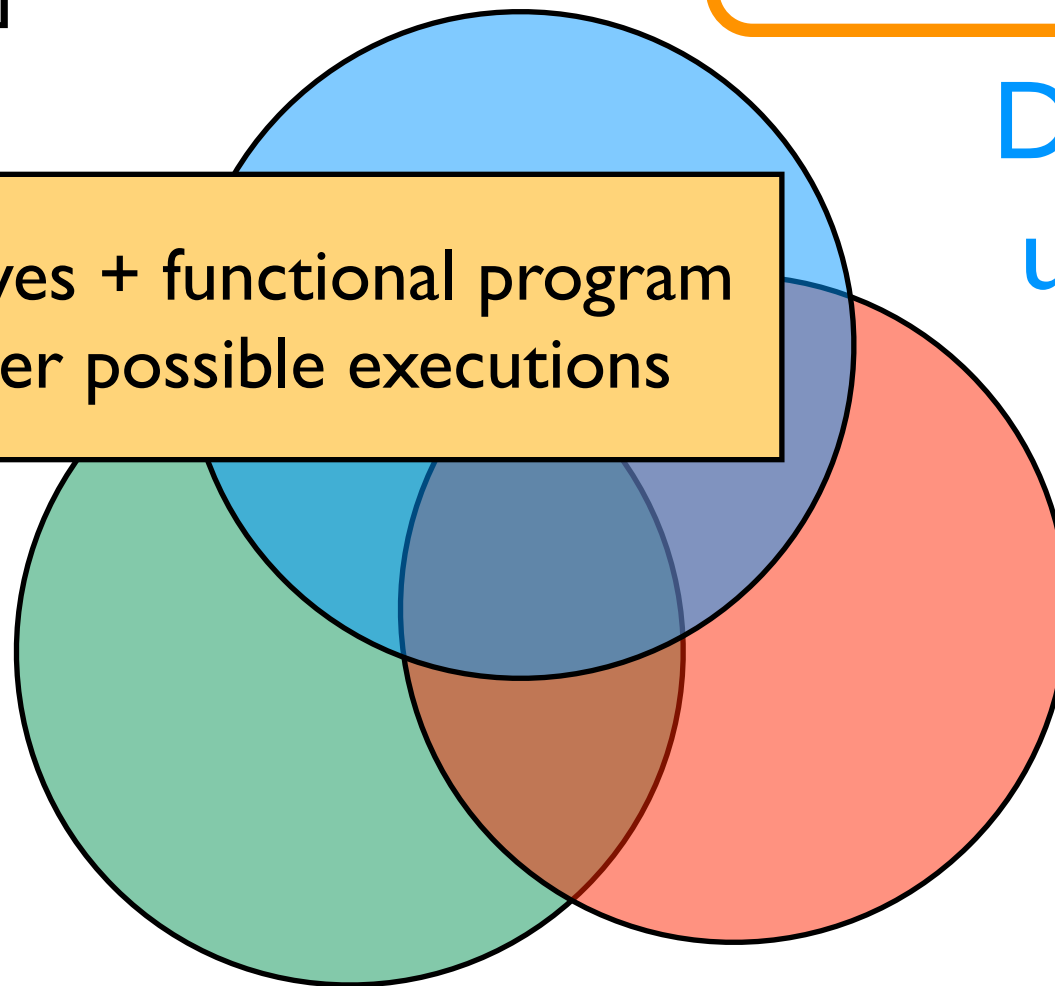
probabilistic primitives + functional program
→ distribution over possible executions

Dealing with
primitives

Reasoning with
probabilistic data

one execution

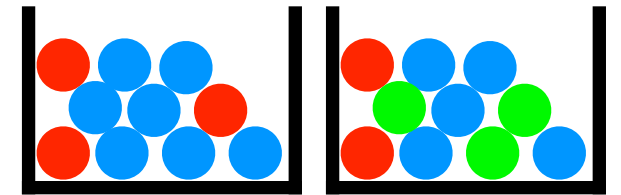
```
(define plus5 (lambda (x) (+ x 5)))  
  
(map plus5 '(1 2 3))
```



Learning

Church by example:

A bit of gambling



- toss (biased) coin & draw ball from each urn
- win if (heads and a red ball) or (two balls of same color)

```
(define heads (mem (lambda () (flip 0.4))))  
  
(define color1 (mem (lambda () (if (flip 0.3) 'red 'blue))))  
  
(define color2 (mem (lambda ()  
                      (multinomial '(red green blue) '(0.2 0.3 0.5))))))  
  
(define redball (or (equal? (color1) 'red) (equal? (color2) 'red)))  
  
(define win1 (and (heads) redball))  
  
(define win2 (equal? (color1) (color2)))  
  
(define win (or win1 win2))
```

Probabilistic Programming Summary

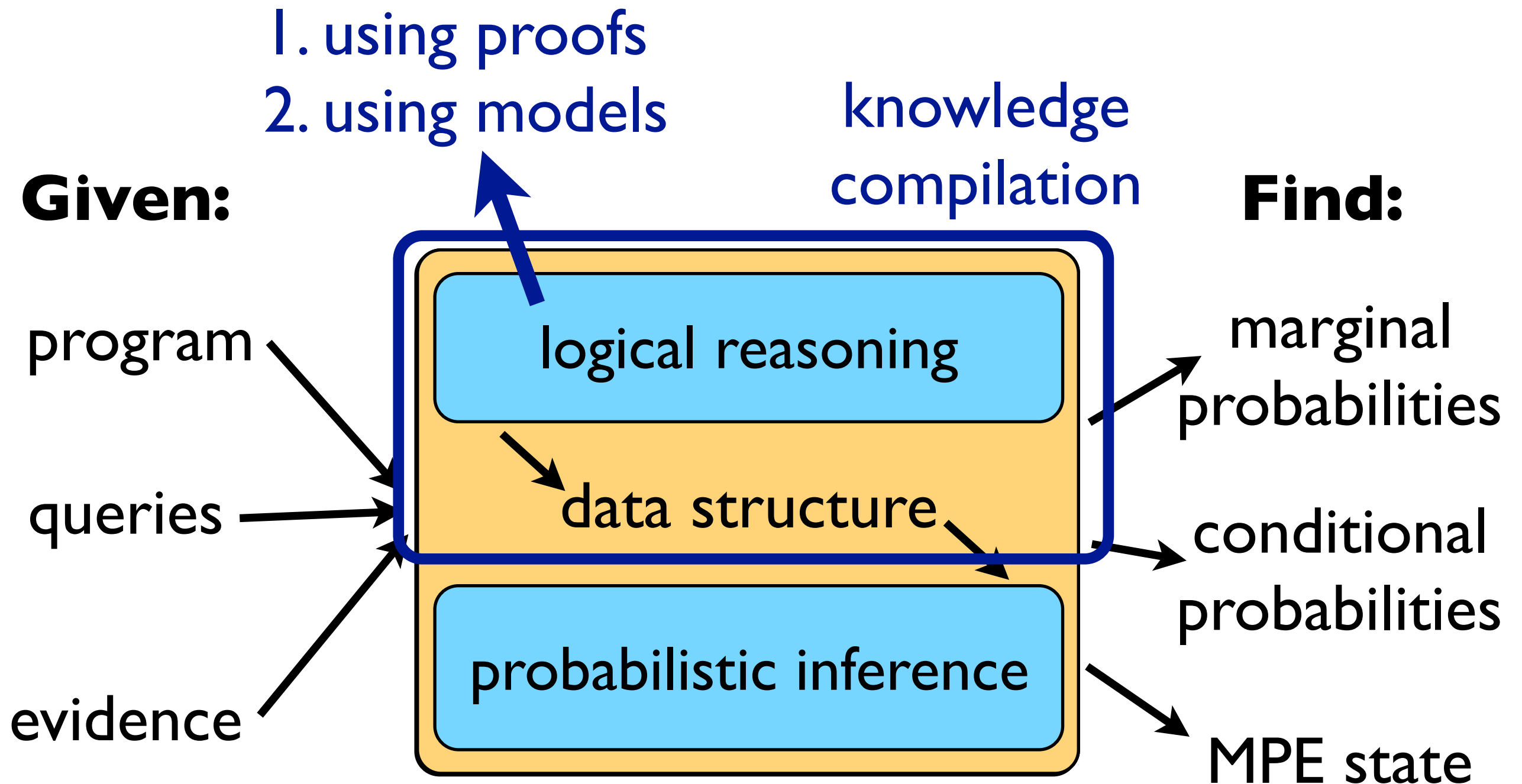
- Church: functional programming + random primitives
- probabilistic generative model
- stochastic memoization
- sampling
- increasing number of probabilistic programming languages using various underlying paradigms

Roadmap

- Modeling (ProbLog and Church, another representative of PP)
- Inference
- Learning
- Dynamics and Decisions

... with some detours on the way

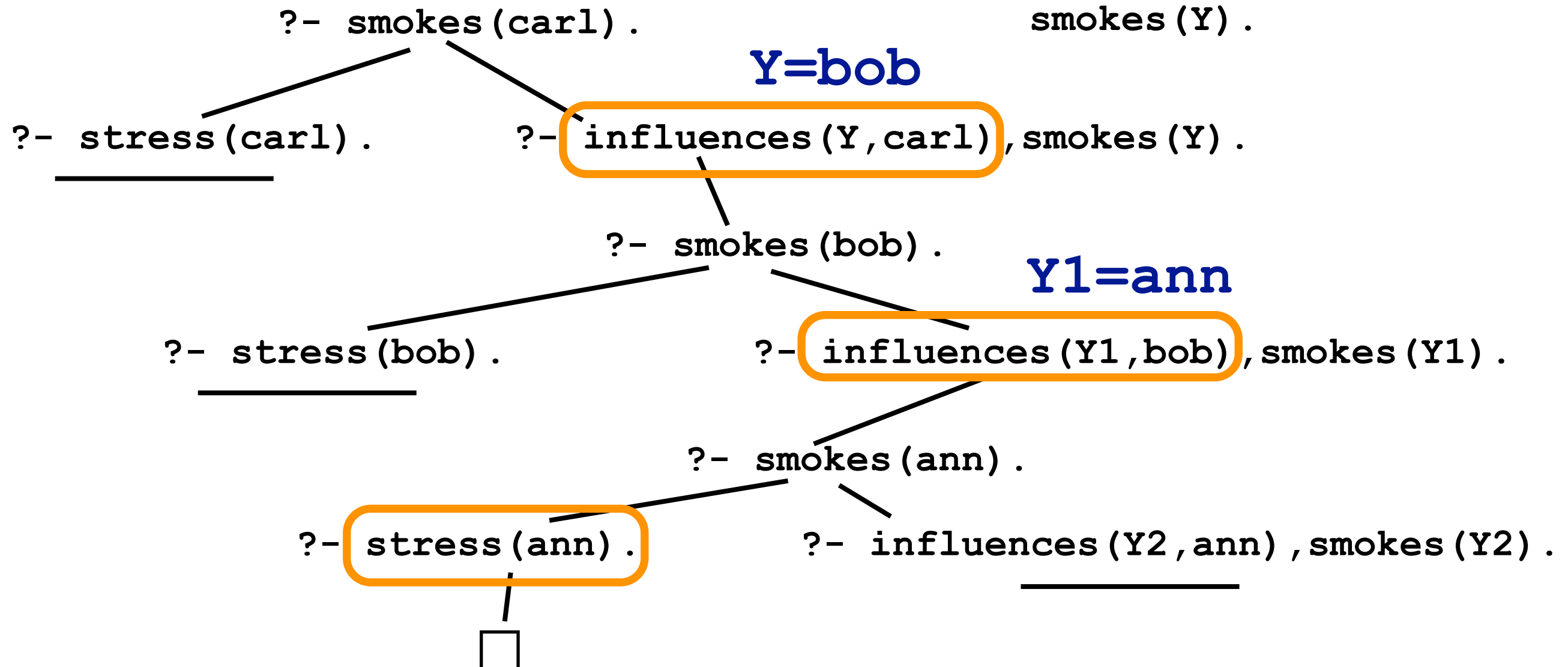
Answering Questions



Proofs in ProbLog

```
0.8::stress(ann).
0.6::influences(ann,bob).
0.2::influences(bob,carl).
```

```
smokes(X) :- stress(X).
smokes(X) :-
    influences(Y,X),
    smokes(Y).
```



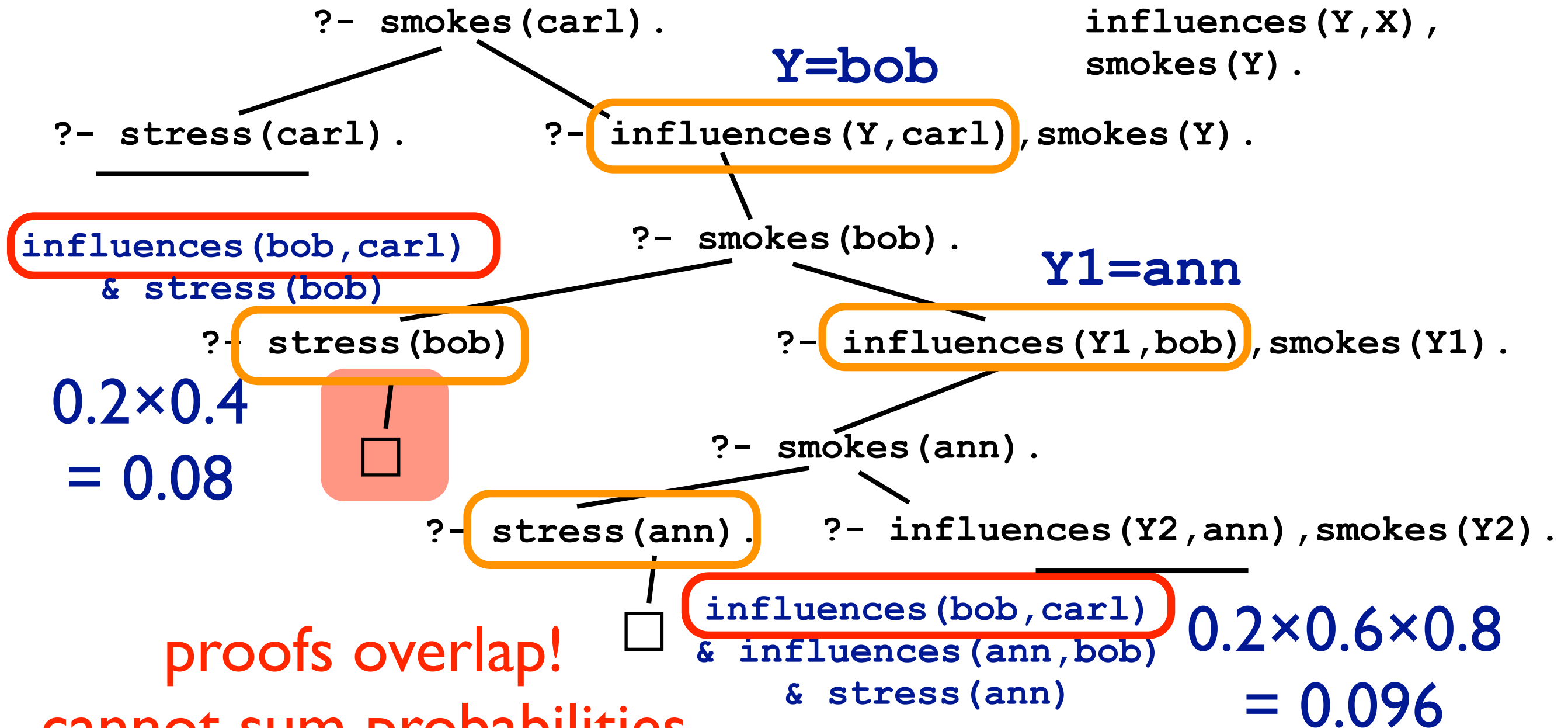
$\text{influences}(\text{bob}, \text{carl}) \ \& \ \text{influences}(\text{ann}, \text{bob}) \ \& \ \text{stress}(\text{ann})$

probability of proof = $0.2 \times 0.6 \times 0.8 = 0.096$

Proofs in ProbLog

```
0.8::stress(ann).
0.4::stress(bob).
0.6::influences(ann,bob).
0.2::influences(bob,carl).
```

```
smokes(X) :- stress(X).
smokes(X) :-
    influences(Y,X),
    smokes(Y).
```



proofs overlap!
cannot sum probabilities
(disjoint-sum-problem)

Disjoint-Sum-Problem

possible worlds

solution: knowledge compilation

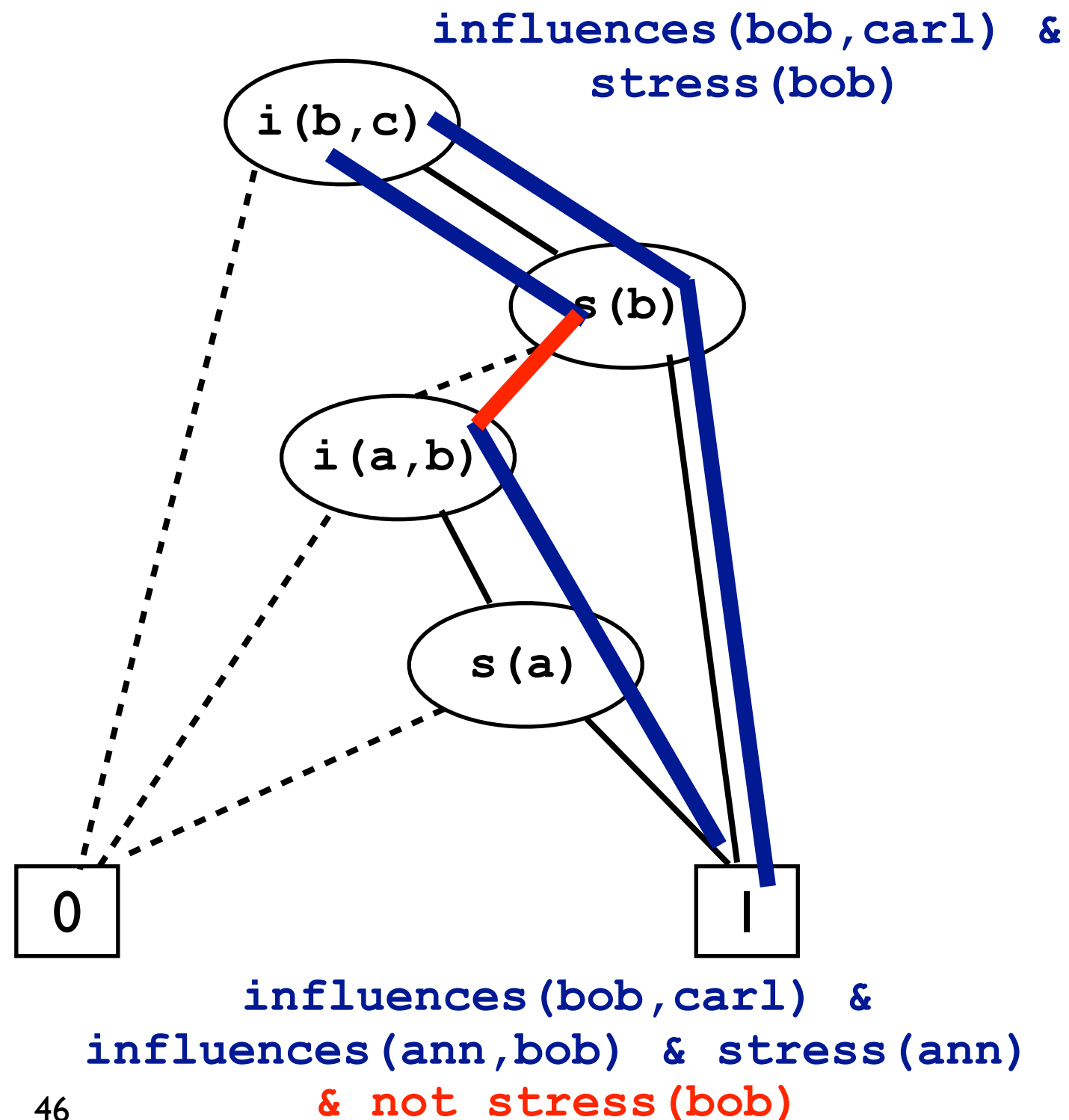
<code>infl(bob,carl) & infl(ann,bob) & st(ann) & \+st(bob)</code>	0.0576
<code>infl(bob,carl) & infl(ann,bob) & st(ann) & st(bob)</code>	0.0384
<code>infl(bob,carl) & \+infl(ann,bob) & st(ann) & st(bob)</code>	0.0256
<code>infl(bob,carl) & infl(ann,bob) & \+st(ann) & st(bob)</code>	0.0096
<code>infl(bob,carl) & \+infl(ann,bob) & \+st(ann) & st(bob)</code>	0.0064

... `influences(bob,carl) & stress(bob)` $\Sigma = 0.1376$

sum of proof probabilities: $0.096 + 0.08 = 0.1760$

Binary Decision Diagrams [Bryant 86]

- compact graphical representation of Boolean formula
- automatically disjoins proofs
- popular in many branches of CS



Binary Decision Diagrams

[Bryant 86]

- compact graphical representation of Boolean formula
- popular in many branches of CS
- automatically disjoins proofs
→ efficient probability computation
- other representations exist (SDDs, d-DNNFs)
- knowledge compilation is state of the art for probabilistic inference (Darwiche et al.)

Answering Questions

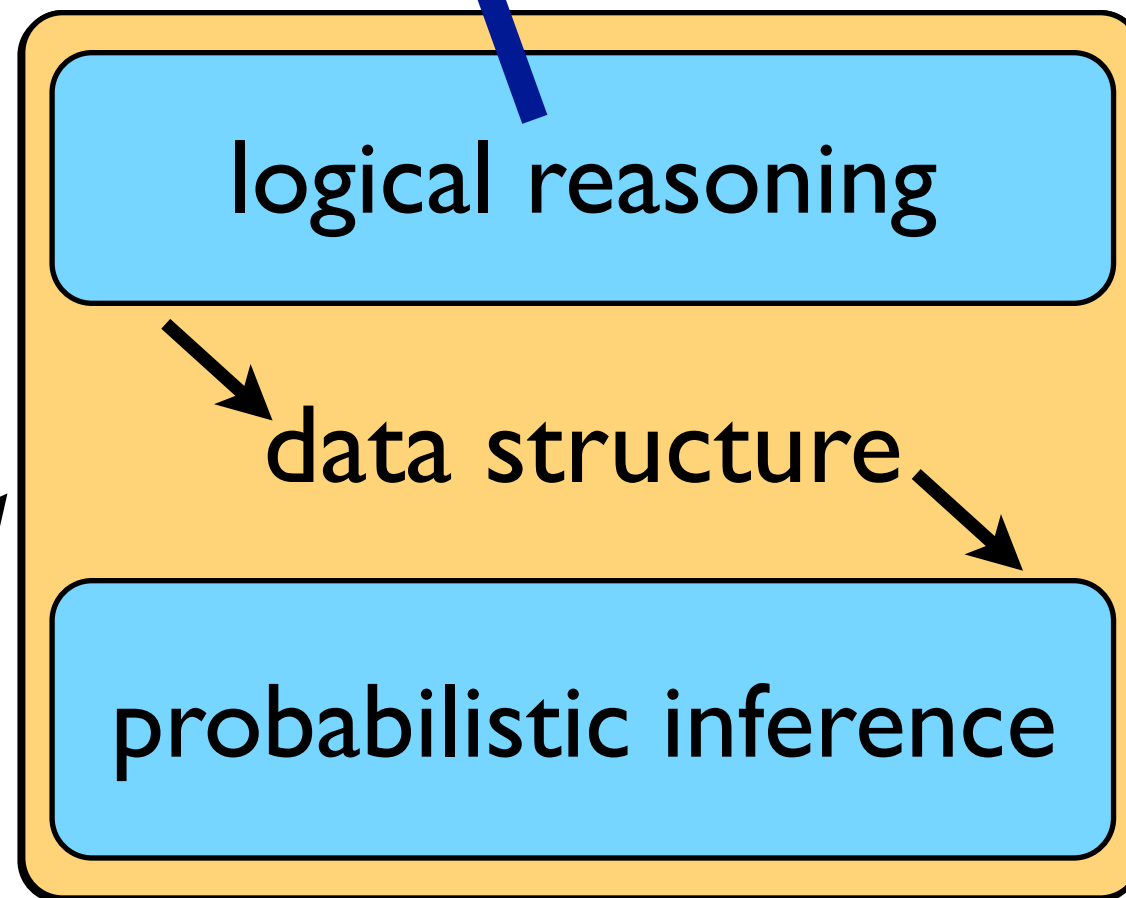
1. using proofs
2. using models

Given:

program

queries

evidence



Find:

marginal
probabilities

conditional
probabilities

MPE state

Current Approach

(ProbLog2)

```
0.4::heads(1).
0.7::heads(2).
0.5::heads(3).
win :- heads(1).
win :- heads(2),
      heads(3).
```

Find relevant ground
program for queries &
evidence

win

Weighted CNF

use weighted model
counting / satisfiability

```
win :- heads(1).
win :- heads(2), heads(3).
```

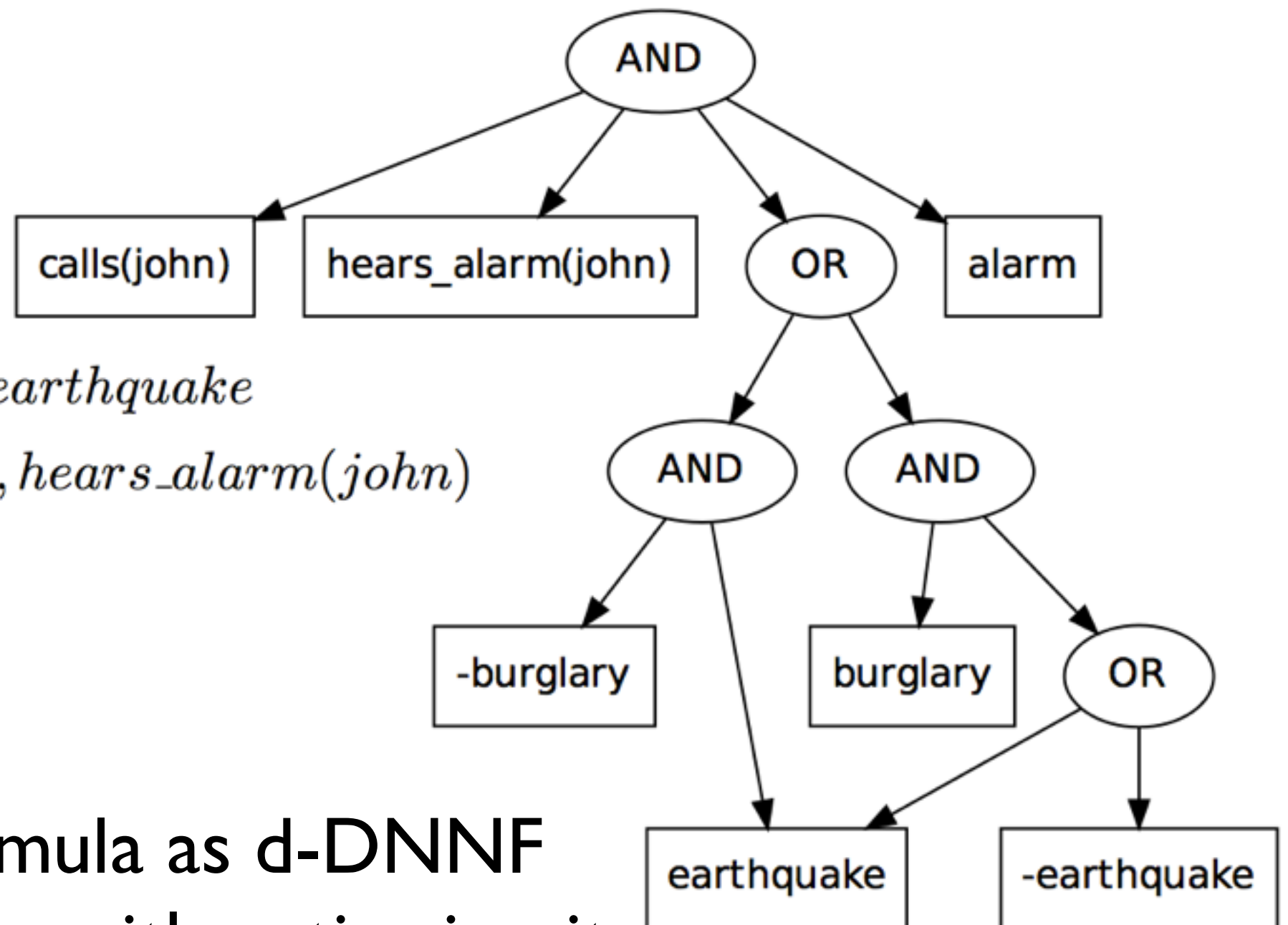
$\text{win} \leftrightarrow h(1) \vee (h(2) \wedge h(3))$

$(\neg \text{win} \vee h(1) \vee h(2))$
 $\wedge (\neg \text{win} \vee h(1) \vee h(3))$
 $\wedge (\text{win} \vee \neg h(1))$
 $\wedge (\text{win} \vee \neg h(2) \vee \neg h(3))$

use
standard
solver

$h(1) \rightarrow 0.4$	$h(2) \rightarrow 0.7$	$h(3) \rightarrow 0.5$
$\neg h(1) \rightarrow 0.6$	$\neg h(2) \rightarrow 0.3$	$\neg h(3) \rightarrow 0.5$

WMC using d-DNNFs



$alarm \leftrightarrow burglary \vee earthquake$

$calls(john) \leftrightarrow alarm, hears_alarm(john)$

$calls(john)$

1. represent formula as d-DNNF
2. transform into arithmetic circuit
3. evaluate bottom-up

Markov Chain Monte Carlo (MCMC)

- Generate next sample by modifying current one
- Most common inference approach for PP languages such as Church, BLOG, ...
- Also considered for PRISM and ProbLog

Key challenges:

- how to propose next sample
- how to handle evidence

Roadmap

- Modeling (ProbLog and Church, another representative of PP)
- Inference
- Learning
- Dynamics and Decisions

... with some detours on the way

Parameter Learning

e.g., webpage classification model

for each *CLASS1*, *CLASS2* and each *WORD*

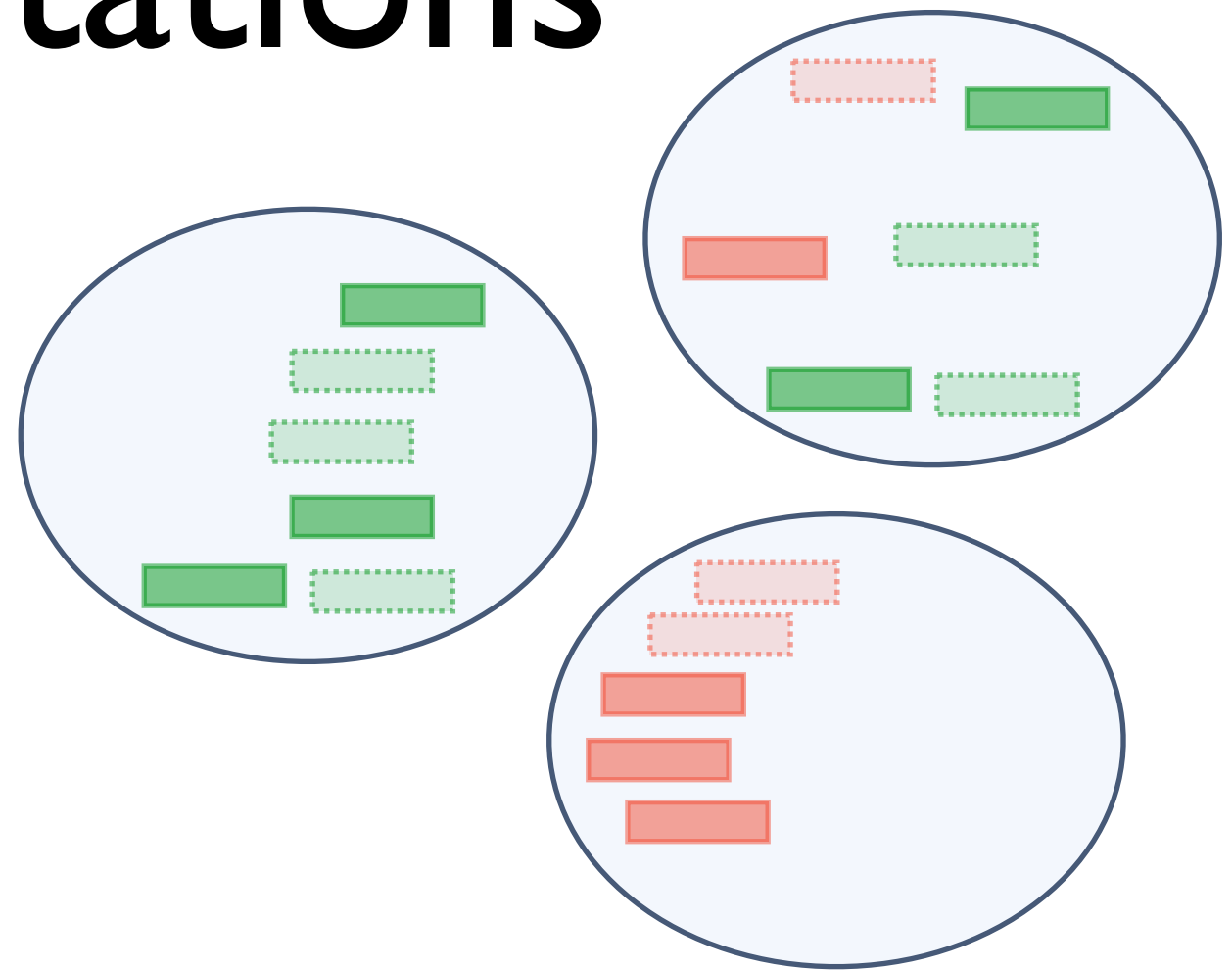
```
?? :: link_class(Source,Target,CLASS1,CLASS2).
```

```
?? :: word_class(WORD,CLASS).
```

```
class(Page,C) :- has_word(Page,W), word_class(W,C).
```

```
class(Page,C) :- links_to(OtherPage,Page),  
    class(OtherPage,OtherClass),  
    link_class(OtherPage,Page,OtherClass,C).
```

Learning from partial interpretations



- Not all facts observed
- Soft-EM
- use expected count instead of count
- $P(Q | E)$ -- conditional queries !

Rule learning — NELL

Table 5: Number of facts per predicate (NELL athlete dataset)

athletecoach(person,person)	18	athleteplaysforteam(person,team)	721
athleteplayssport(person,sport)	1921	teamplaysinleague(team,league)	1085
athleteplaysinleague(person,league)	872	athletealsoknownas(person,name)	17
coachesinleague(person,league)	93	coachesteam(person,team)	132
teamhomestadium(team,stadium)	198	teamplayssport(team,sport)	359
athleteplayssportsteamposition(person,position)	255	athletehomestadium(person,stadium)	187
athlete(person)	1909	attraction(stadium)	2
coach(person)	624	female(person)	2
male(person)	7	hobby(sport)	5
organization(league)	1	person(person)	2
personafrika(person)	1	personasia(person)	4
personaaustralia(person)	22	personcanada(person)	1
personeurope(person)	1	personmexico(person)	108
personus(person)	6	sport(sport)	36
sportsleague(league)	18	sportsteam(team)	1330
sportsteamposition(position)	22	stadiumoreventvenue(stadium)	171

Adaptation of standard rule learning and
inductive logic programming setting
[De Raedt et al IJCAI 15]

Experiments

Table 4: Precision for different experimental setups and parameters ($A: m = 1, p = 0.99, B: m = 1000, p = 0.90$).

Setting train/test/rule	athleteplaysforteam		athleteplayssport		teamplaysinleague		athleteplaysinleague		teamplaysagainstteam	
	A	B	A	B	A	B	A	B	A	B
1: det/det/det	74.00	69.36	94.14	93.47	96.29	82.15	80.95	74.14	73.40	73.86
2: det/prob/det	73.51	69.57	97.53	94.85	96.70	87.83	90.83	77.73	73.70	73.35
3: det/prob/prob	74.67	69.82	95.86	94.74	96.35	82.57	82.26	75.29	73.84	74.34
4: det/prob/prob	77.25	73.87	96.53	96.04	98.00	90.59	84.91	79.36	77.26	77.83
5: det/prob/prob	74.76	69.97	95.85	94.69	96.44	82.51	81.99	75.07	73.90	74.16
6: prob/prob/det	75.83	73.11	93.40	93.76	94.44	93.67	79.41	79.42	80.87	80.60
7: prob/prob/prob	78.31	73.72	95.62	95.10	98.84	91.86	96.94	79.49	85.78	81.81

Table 3: Learned relational rules for the different predicates (fold 1).

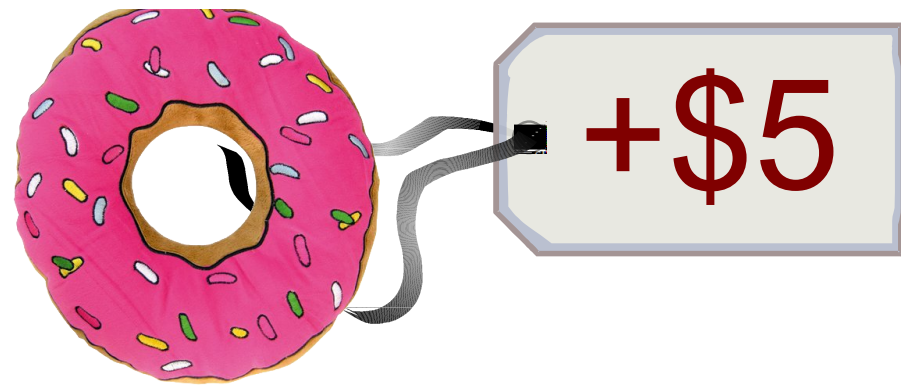
0.9375::athleteplaysforteam(A,B)	←	athleleedsportsteam(A,B).
0.9675::athleteplaysforteam(A,B)	←	athleleedsportsteam(A,V1), teamplaysagainstteam(B,V1).
0.9375::athleteplaysforteam(A,B)	←	athleteplayssport(A,V1), teamplayssport(B,V1).
0.5109::athleteplaysforteam(A,B)	←	athleteplaysinleague(A,V1), teamplaysinleague(B,V1).
0.9070::athleteplayssport(A,B)	←	athleleedsportsteam(A,V2), teamalsoknownas(V2,V1), teamplayssport(V1,B), teamplayssport(V2,B).
0.9070::athleteplayssport(A,B)	←	athleteplaysforteam(A,V2), teamalsoknownas(V2,V1), teamplayssport(V1,B), teamplayssport(V2,B), teamalsoknownas(V1,V2).
0.9070::athleteplayssport(A,B)	←	athleteplaysforteam(A,V1), teamplayssport(V1,B).
0.9286::athleteplaysinleague(A,B)	←	athleleedsportsteam(A,V1), teamplaysinleague(V1,B).
0.7868::athleteplaysinleague(A,B)	←	athleteplaysforteam(A,V2), teamalsoknownas(V2,V1), teamplaysinleague(V1,B).
0.9384::athleteplaysinleague(A,B)	←	athleteplayssport(A,V2), athleteplayssport(V1,V2), teamplaysinleague(V1,B).
0.9024::athleteplaysinleague(A,B)	←	athleteplaysforteam(A,V1), teamplaysinleague(V1,B).

Roadmap

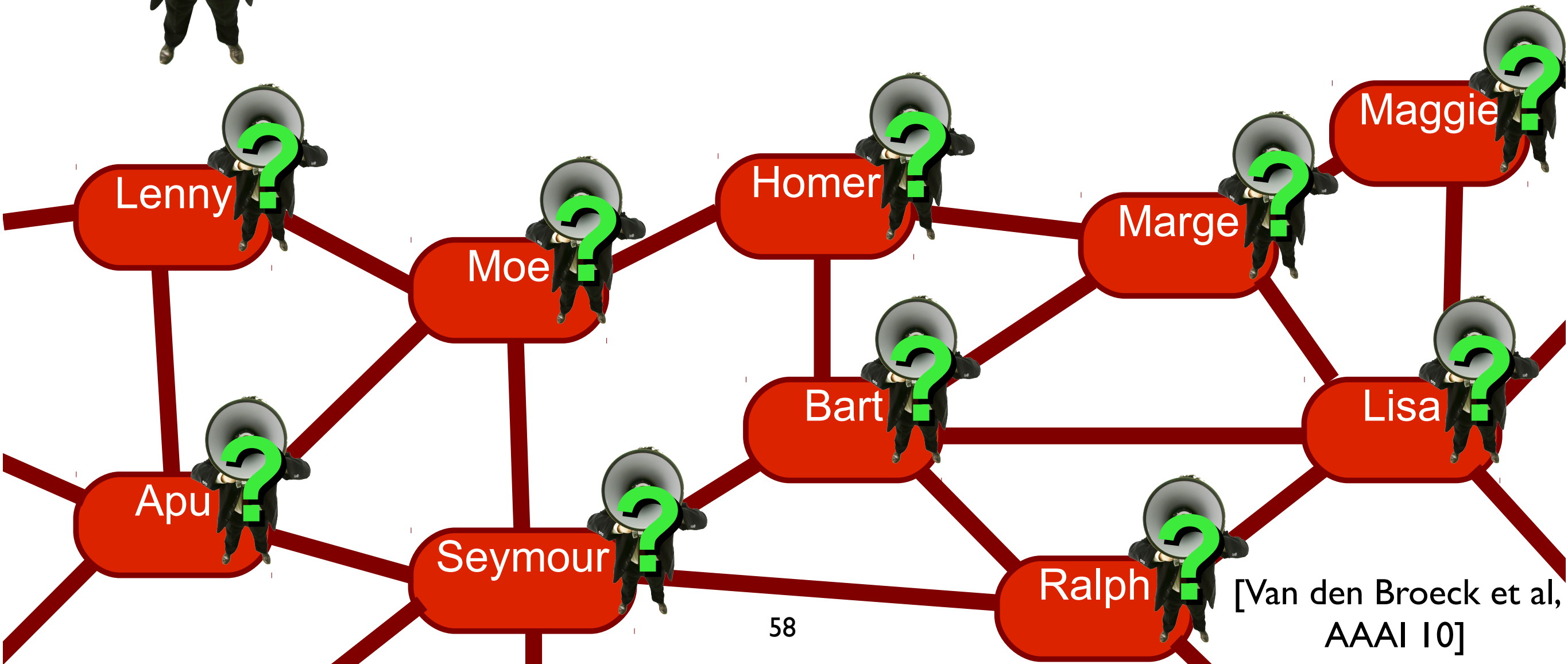
- Modeling (ProbLog and Church, another representative of PP)
- Inference
- Learning
- Dynamics and Decisions

... with some detours on the way

Viral Marketing



Which advertising
decide truth values of
strategy maximizes
some atoms,
expected profit?



DTPProbLog

```
? :: marketed(P) :- person(P) .
```

```
0.3 :: buy_trust(X,Y) :- friend(X,Y) .
0.2 :: buy_marketing(P) :- person(P) .
```

decision fact: true or false?

```
buys(X) :- friend(X,Y) , buys(Y) , buy_trust(X,Y) .
buys(X) :- marketed(X) , buy_marketing(X) .
```

```
buys(P) => 5 :- person(P) .
marketed(P) => -3 :- person(P) .
```

probabilistic facts

logical rules

utility facts: cost/reward if true

probability = 0.0032

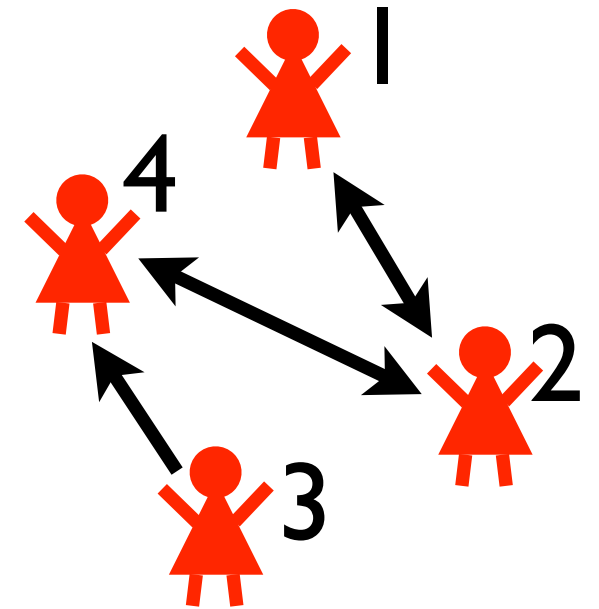
```
marketed(1)          marketed(3)
```

```
bt(2,1)  bt(2,4)  bm(1)
```

```
buys(1)  buys(2)
```

task: find strategy that maximizes expected utility

solution: using ProbLog technology



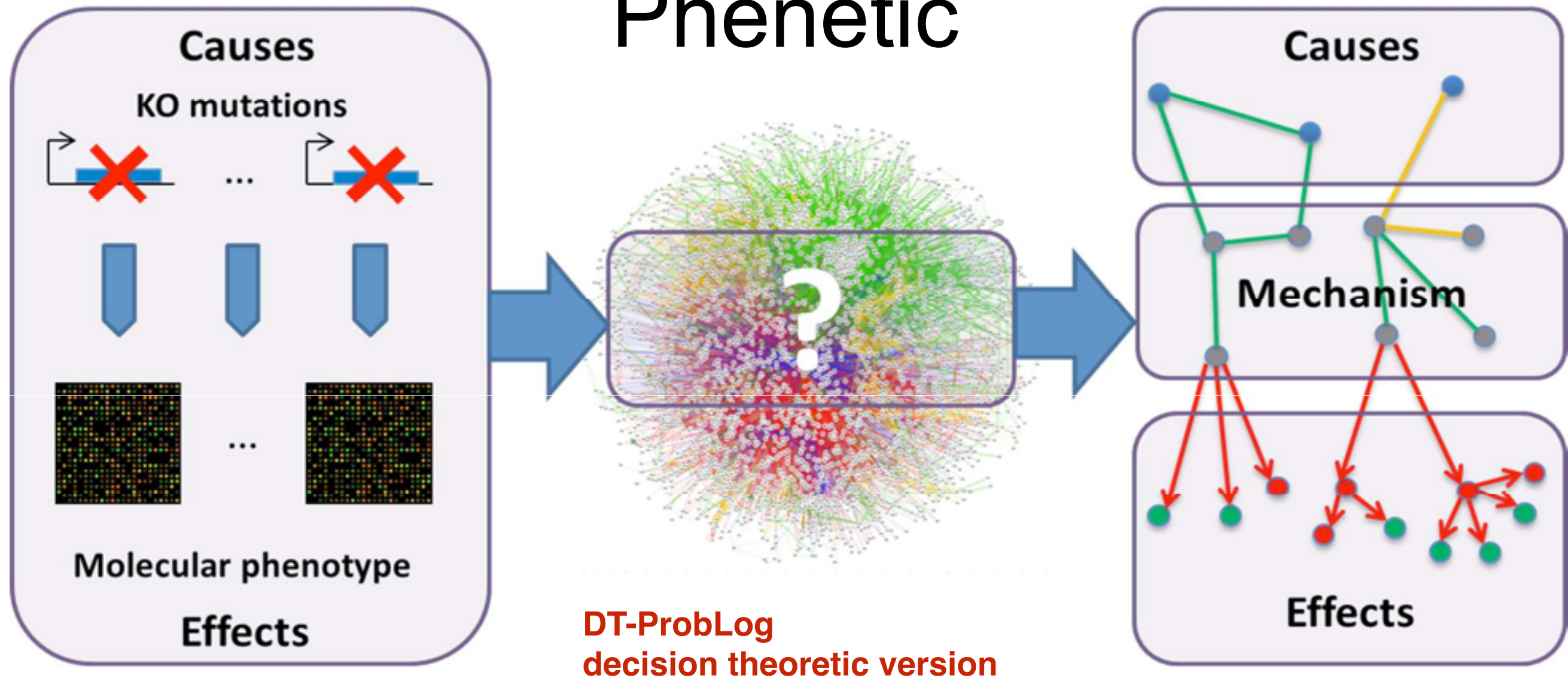
```
person(1) .
person(2) .
person(3) .
person(4) .
```

```
friend(1,2) .
friend(2,1) .
friend(2,4) .
friend(3,4) .
friend(4,2) .
```

world contributes

strategy

Phenetic



- Causes: Mutations
 - All related to similar phenotype
- Effects: Differentially expressed genes
 - 27 000 cause effect pairs

- Interaction network:
 - 3063 nodes
 - Genes
 - Proteins
 - 16794 edges
 - Molecular interactions
 - Uncertain

- Goal: connect causes to effects through common subnetwork
 - = Find mechanism
- Techniques:
 - DTProbLog [Van den Broeck]
 - Approximate inference

Can we find the mechanism connecting causes to effects?

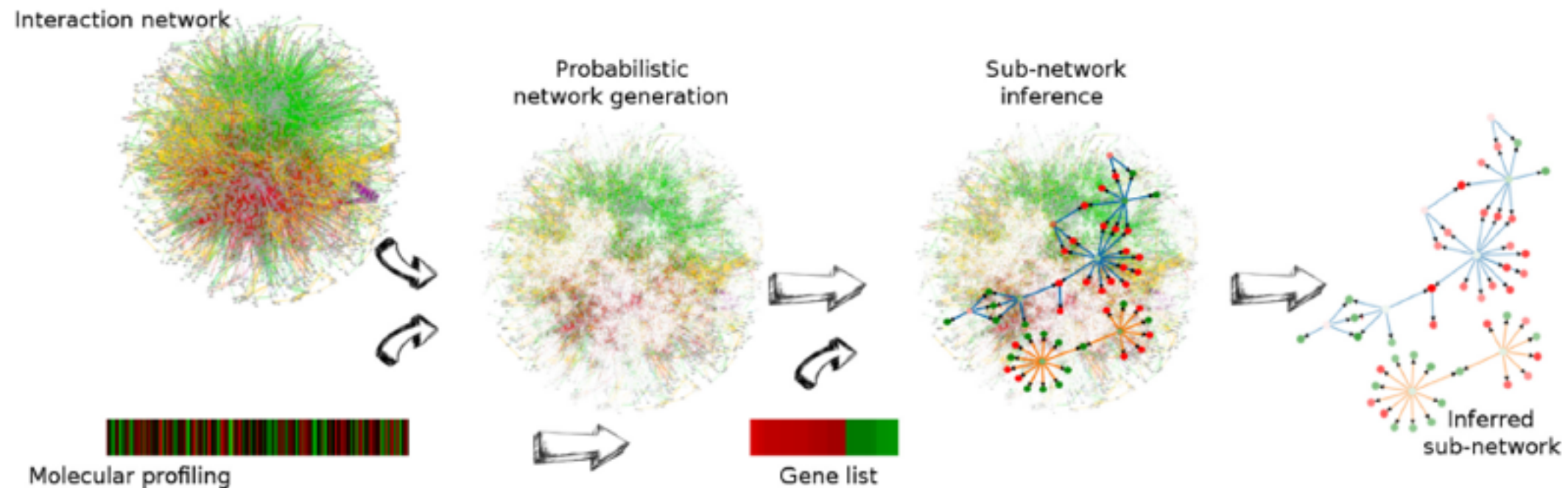


Figure 1. Overview of PheNetic, a web service for network-based interpretation of 'omics' data. The web service uses as input a genome wide interaction network for the organism of interest, a user generated molecular profiling data set and a gene list derived from these data. Interaction networks for a wide variety of organisms are readily available from the web server. Using the uploaded user-generated molecular data the interaction network is converted into a probabilistic network: edges receive a probability proportional to the levels measured for the terminal nodes in the molecular profiling data set. This probabilistic interaction network is used to infer the sub-network that best links the genes from the gene list. The inferred sub-network provides a trade-off between linking as many genes as possible from the gene list and selecting the least number of edges.

[De Mayer et al., NAR 15]

A true application

A tool for Computational Biology

Based on decision theoretic variation of ProbLog

ProbLog / Prob. Programming for prototyping

More specialised inference engine was needed

also some special purpose approximations

Distributional Clauses (DC)

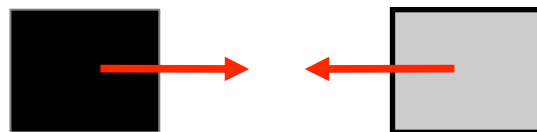
- A probabilistic logic language
- Logic (relational): a template to define random variables
- MDP representation in Dynamic DC:
 - Transition model: $\text{Head}_{t+1} \sim \text{Distribution} \leftarrow \text{Conditions}_t$
 - Applicable actions: $\text{applicable}(\text{Action})_t \leftarrow \text{Conditions}_t$
 - Reward: $\text{reward}(R)_t \leftarrow \text{Conditions}_t$
 - Terminal state: $\text{stop}_t \leftarrow \text{Conditions}_t$
- The state can contain:
 - Discrete, continuous variables
 - The number of variables in the state can change over time

Magnetic scenario

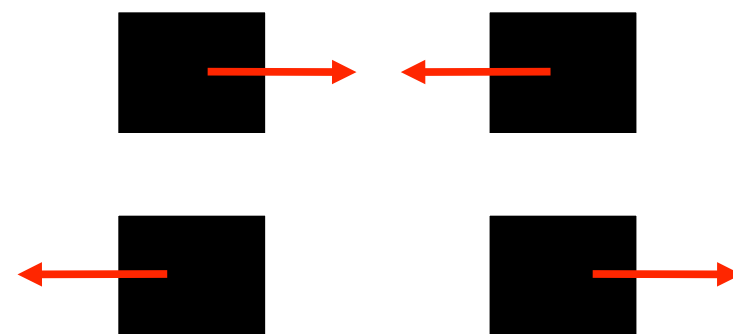
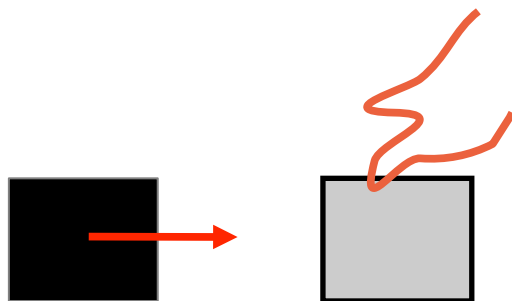
- 3 object types: magnetic, ferromagnetic, nonmagnetic

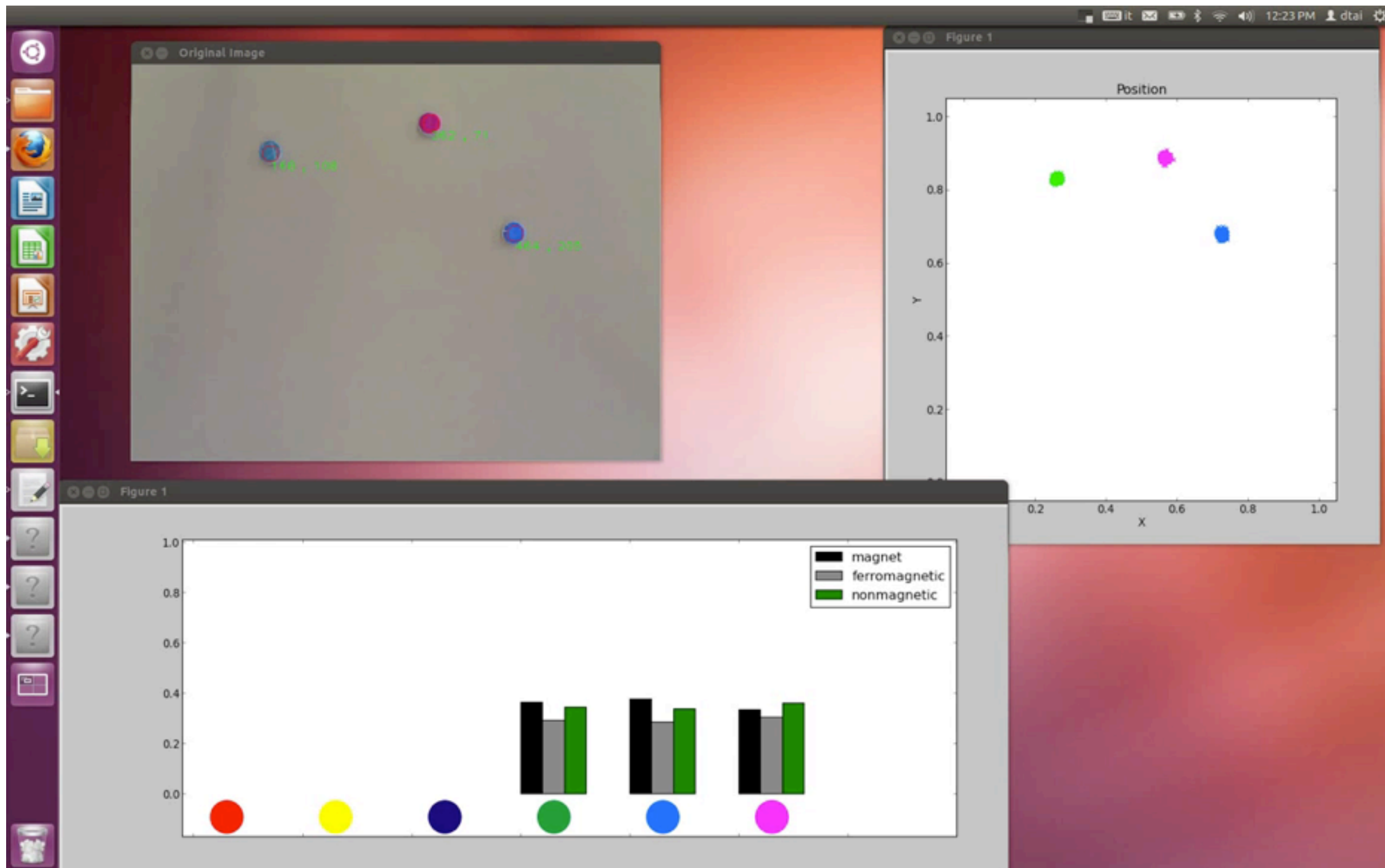


- Nonmagnetic objects do not interact
- A magnet and a ferromagnetic object attract each other



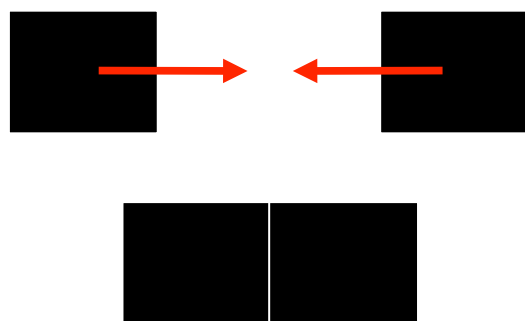
- Magnetic force that depends on the distance
- If an object is held magnetic force is compensated.





Magnetic scenario

- 3 object types: magnetic, ferromagnetic, nonmagnetic
 $\text{type}(X)_t \sim \text{finite}([1/3:\text{magnet}, 1/3:\text{ferromagnetic}, 1/3:\text{nonmagnetic}]) \leftarrow \text{object}(X).$
- 2 magnets attract or repulse
 $\text{interaction}(A,B)_t \sim \text{finite}([0.5:\text{attraction}, 0.5:\text{repulsion}]) \leftarrow \text{object}(A), \text{object}(B), A < B, \text{type}(A)_t = \text{magnet}, \text{type}(B)_t = \text{magnet}.$
- Next position after attraction

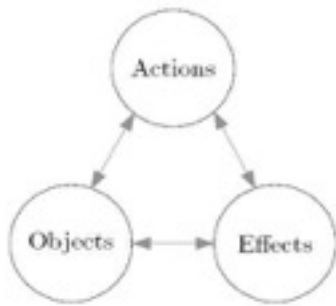


$\text{pos}(A)_{t+1} \sim \text{gaussian}(\text{midpoint}(A,B)_t, \text{Cov}) \leftarrow$
 $\text{near}(A,B)_t, \text{not}(\text{held}(A)), \text{not}(\text{held}(B)),$
 $\text{interaction}(A,B)_t = \text{attr},$
 $c/\text{dist}(A,B)_t^2 > \text{friction}(A)_t.$

$\text{pos}(A)_{t+1} \sim \text{gaussian}(\text{pos}(A)_t, \text{Cov}) \leftarrow \text{not}(\text{attraction}(A,B)).$

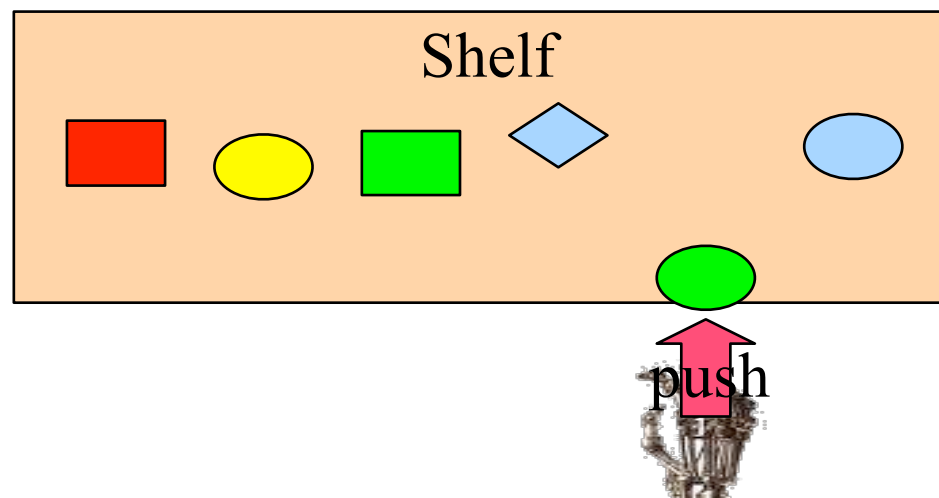
Learning relational affordances

Learn probabilistic model

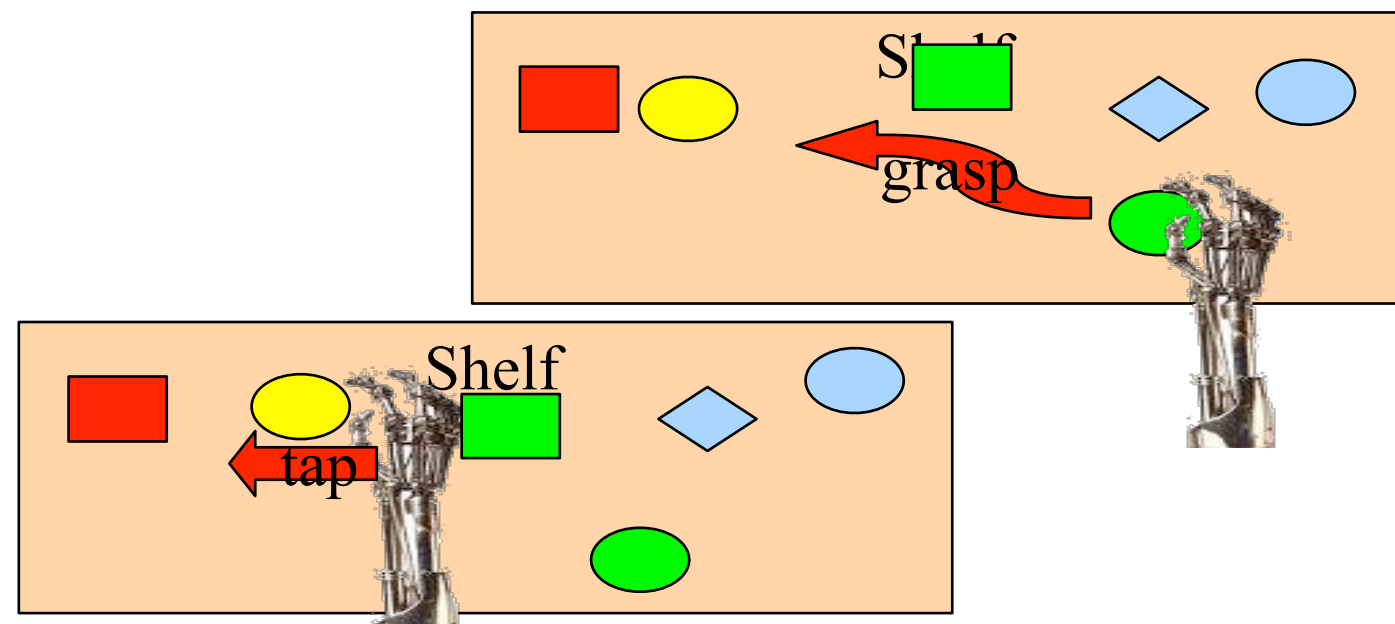


Inputs	Outputs	Function
(O, A)	E	Effect prediction
(O, E)	A	Action recognition/planning
(A, E)	O	Object recognition/selection

From two object interactions
Generalize to N



Moldovan et al. ICRA 12, 13, 14, PhD 15



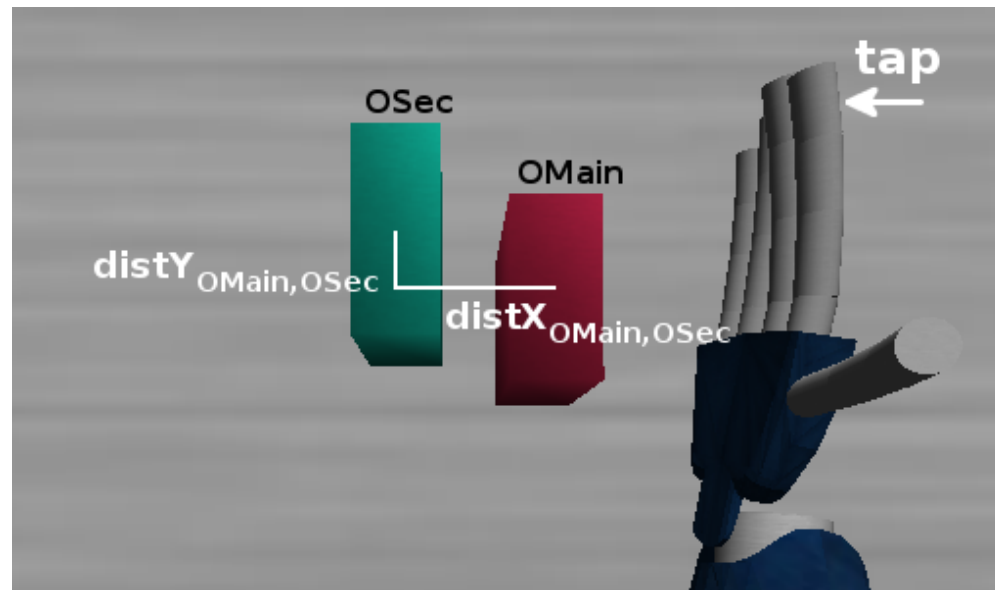
Learning relational
affordances
between
two objects
(learnt by experience)

**Learning relational
affordances
between
two objects
(learnt by experience)**

Right Arm

Examples

What is an affordance ?



Clip 8: Relational O before (l), and E after the action execution (r).

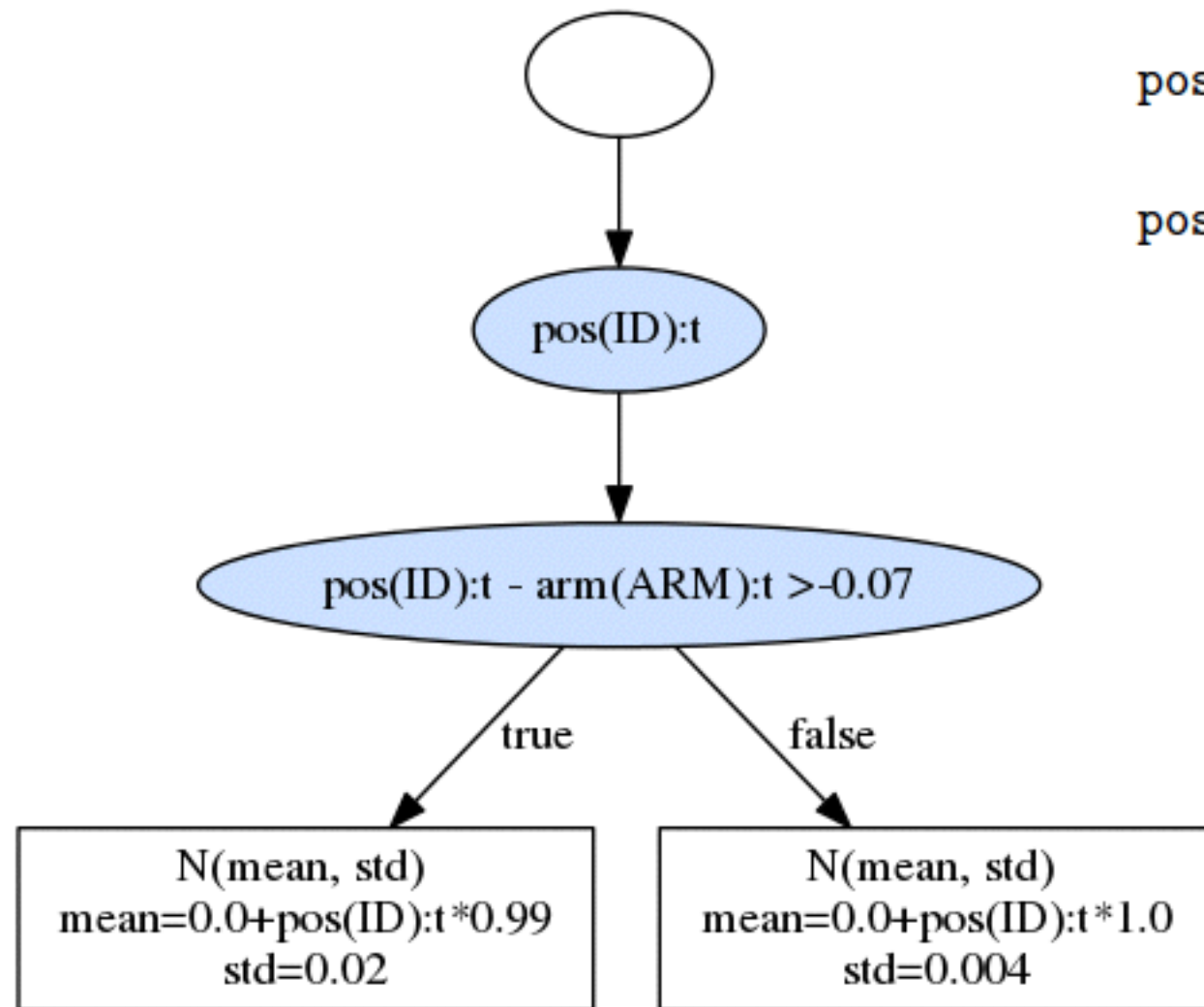
Table 1: Example collected O , A , E data for action in Figure 8

Object Properties	Action	Effects
$shape_{O_{Main}} : sprism$ $shape_{O_{Sec}} : sprism$ $distX_{O_{Main},O_{Sec}} : 6.94cm$ $distY_{O_{Main},O_{Sec}} : 1.90cm$	$tap(10)$	$displX_{O_{Main}} : 10.33cm$ $displY_{O_{Main}} : -0.68cm$ $displX_{O_{Sec}} : 7.43cm$ $displY_{O_{Sec}} : -1.31cm$

- Formalism — related to STRIPS but models delta
- but also joint probability model over A , E , O

Learning the model

Key ideas



$$\begin{aligned} \text{pos}(\text{ID})_{t+1} &\sim \text{gaussian}(0.99 * \simeq \text{pos}(\text{ID})_t, .02) \leftarrow \\ &\quad \simeq \text{pos}(\text{ID})_t - \simeq \text{arm}(\text{ARM})_t > -0.07. \\ \text{pos}(\text{ID})_{t+1} &\sim \text{gaussian}(\simeq (\text{pos}(\text{ID})_t), .004) \leftarrow \\ &\quad \simeq \text{pos}(\text{ID})_t - \simeq \text{arm}(\text{ARM})_t \leq -0.07. \end{aligned}$$

1. Learn a regression tree
2. Map it onto DCs
(satisfies disjointness requirement)
3. Use complex “aggregate” features
4. Use pseudo-likelihood to score

Some non branching nodes ...

Learning the model

Key ideas

Distributions. We envisage the following types of distributions $\mathcal{D}(f_c(s_t))$ in Eq. 5:

- a **linear Gaussian distribution** defining $\mathcal{D}(f_c(s_t)) = N(\mu, \sigma)$ where $\mu = \alpha + \sum_{f \in f_c(s_t)} f_c \cdot \beta_{f_c}$ if Q_{t+1} 's range is continuous
- a **softmax** or normalized exponential model defining $\mathcal{D}(f_c(s_t))$ as a $\text{softmax}(\beta^T f_c(s_t))$ if Q_{t+1} ranges over discrete values, where the β_j are vectors of weights for the vector of features $f_c(s_t)$ and value v_j in Q_{t+1} 's range.

$$\text{agg}\{(U_1 \text{ op } U_2), C\}$$

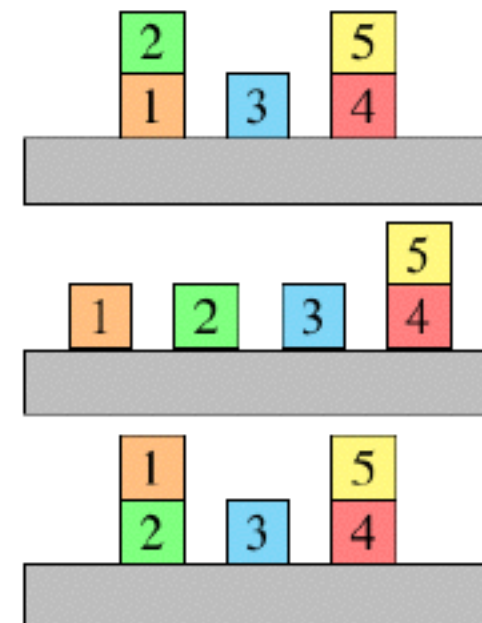
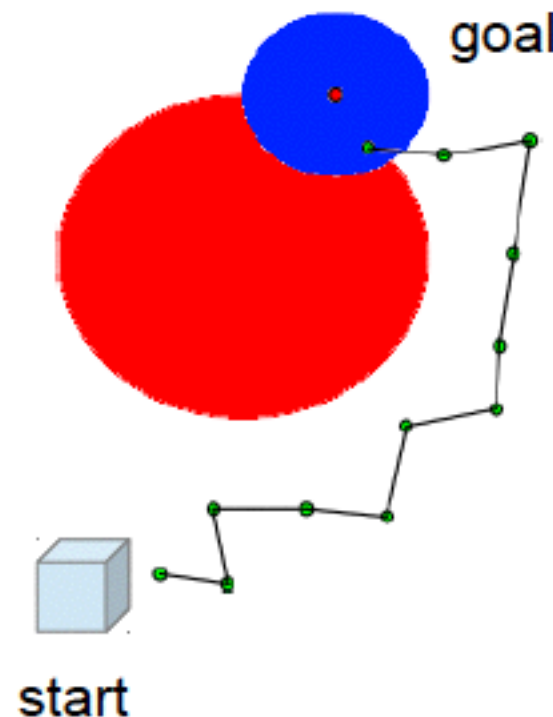
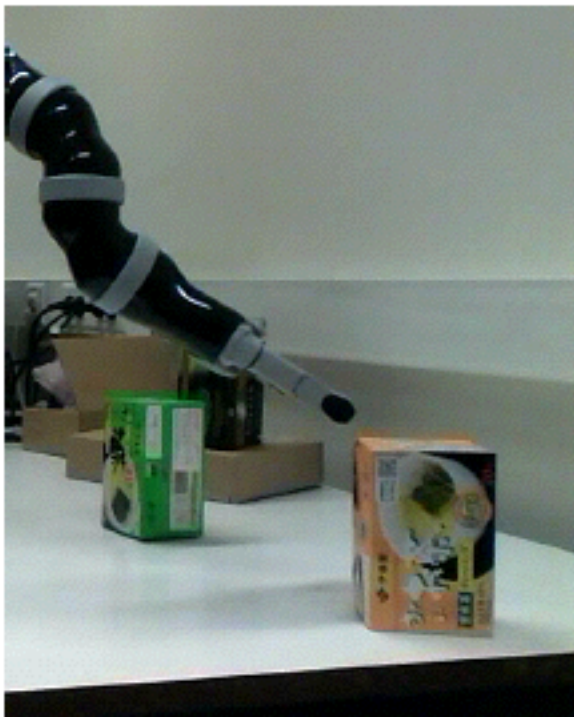
$$\min\{(pos_x(o_1)_t - pos_x(o_2))_t, o_1 \neq o_2\}$$

$$score(DC, e) =$$

$$\sum_{(h \sim \mathcal{D} \leftarrow body) \in DC} \sum_{\theta: body\theta \subseteq I_e} p_{\mathcal{D}}(I(h\theta) | I(body\theta))$$

Planning

- Main task: probabilistic planning
Find the best action to achieve the goal
- Discrete + continuous + relational representation

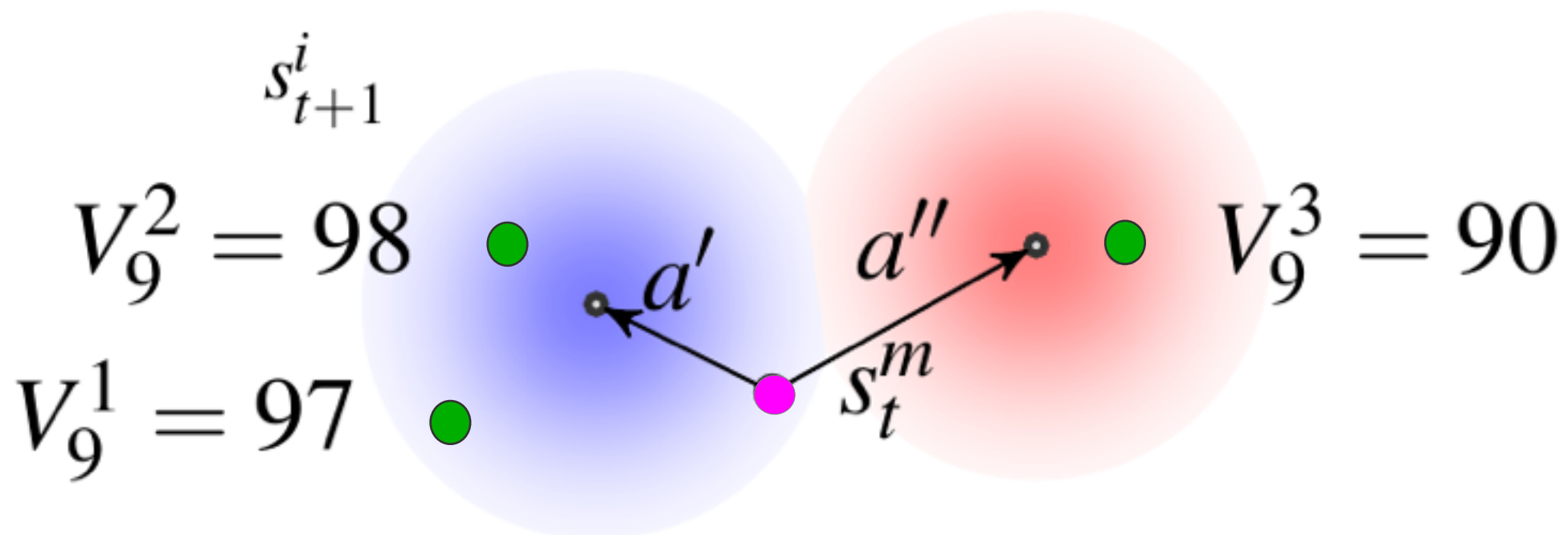
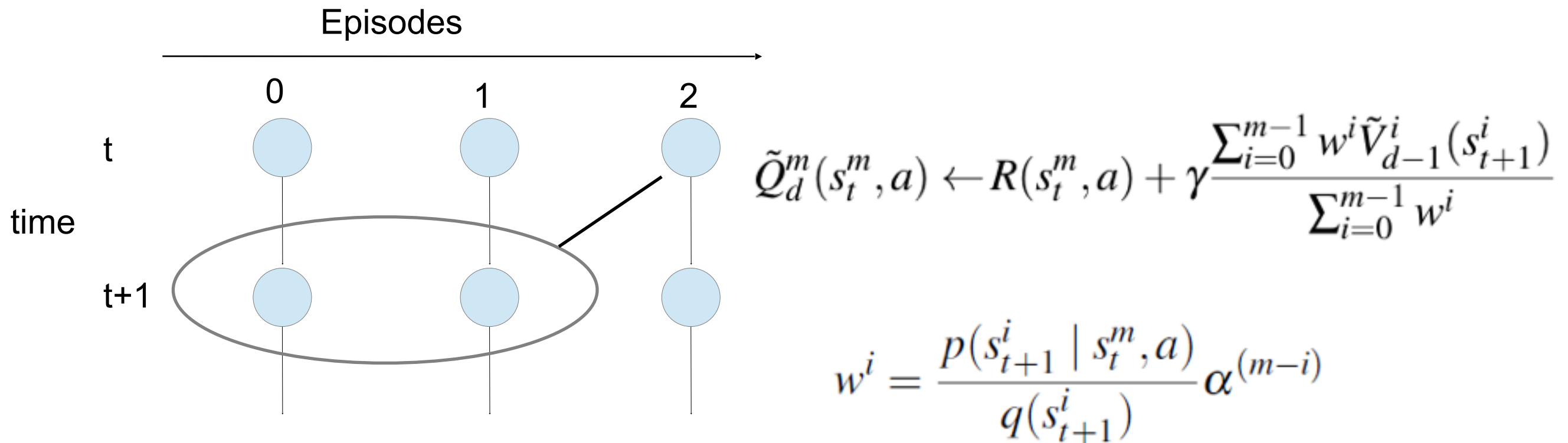


[Nitti et al ECML 15]

How?

- Hybrid relational MDP
- Monte-Carlo (sampling)
- Exploit the model
(sample-based planners do not exploit the MDP model when available)
- Non-parametric (lazy learning)
- Abstract sampled episodes (not states)

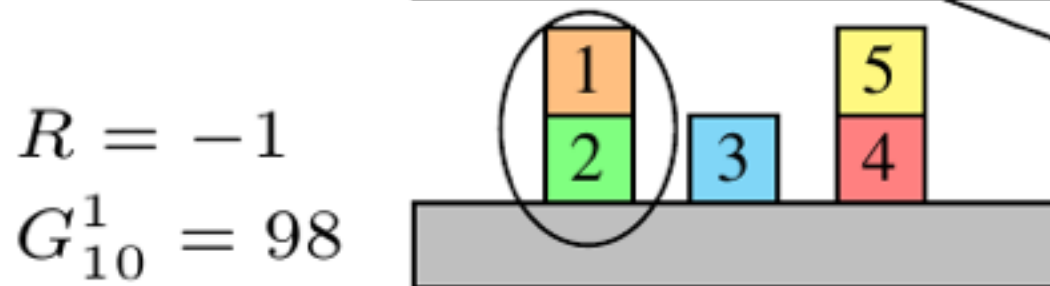
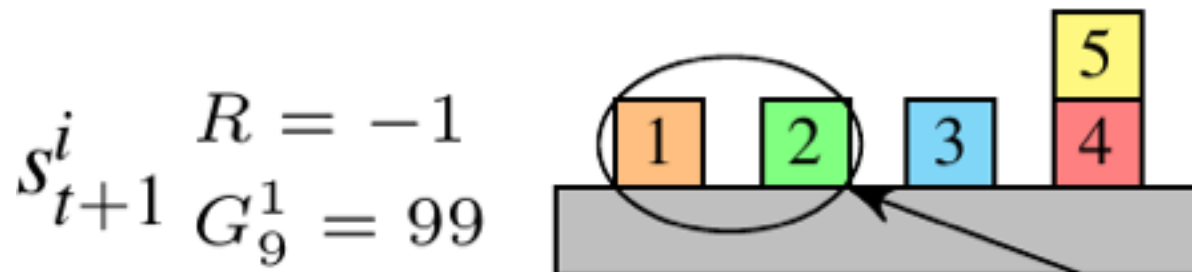
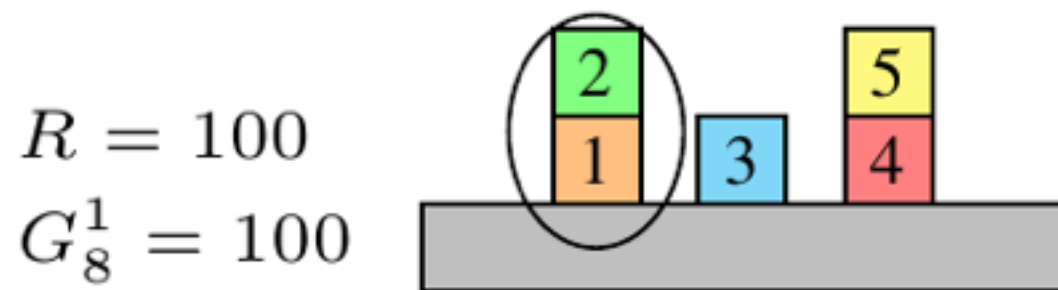
HYPE: Q-function evaluation



Partial interpretations

- Remove irrelevant facts for $\sum R(s_t, a_t)$
- $p(s_{t+1} | s_t, a_t)$ is applied to partial states

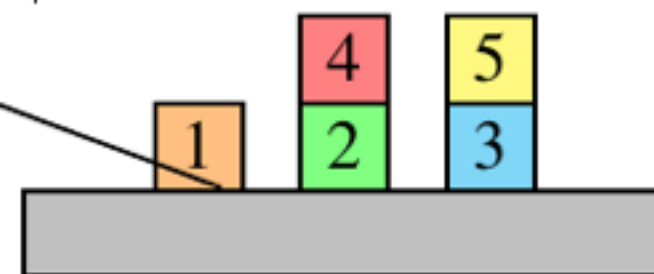
goal on(2,1) with reward 100, -1 otherwise



$$\tilde{Q}_d^m(s_t^m, a) \leftarrow R(s_t^m, a) + \gamma \frac{\sum_{i=0}^{m-1} w^i \tilde{V}_{d-1}^i(s_{t+1}^i)}{\sum_{i=0}^{m-1} w^i}$$

$$w^i = \frac{p(s_{t+1}^i | s_t^m, a)}{q(s_{t+1}^i)} \alpha^{(m-i)}$$

$$p(s'_{t+1} | s_t, a)$$

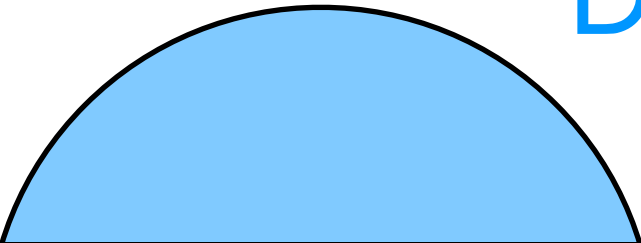
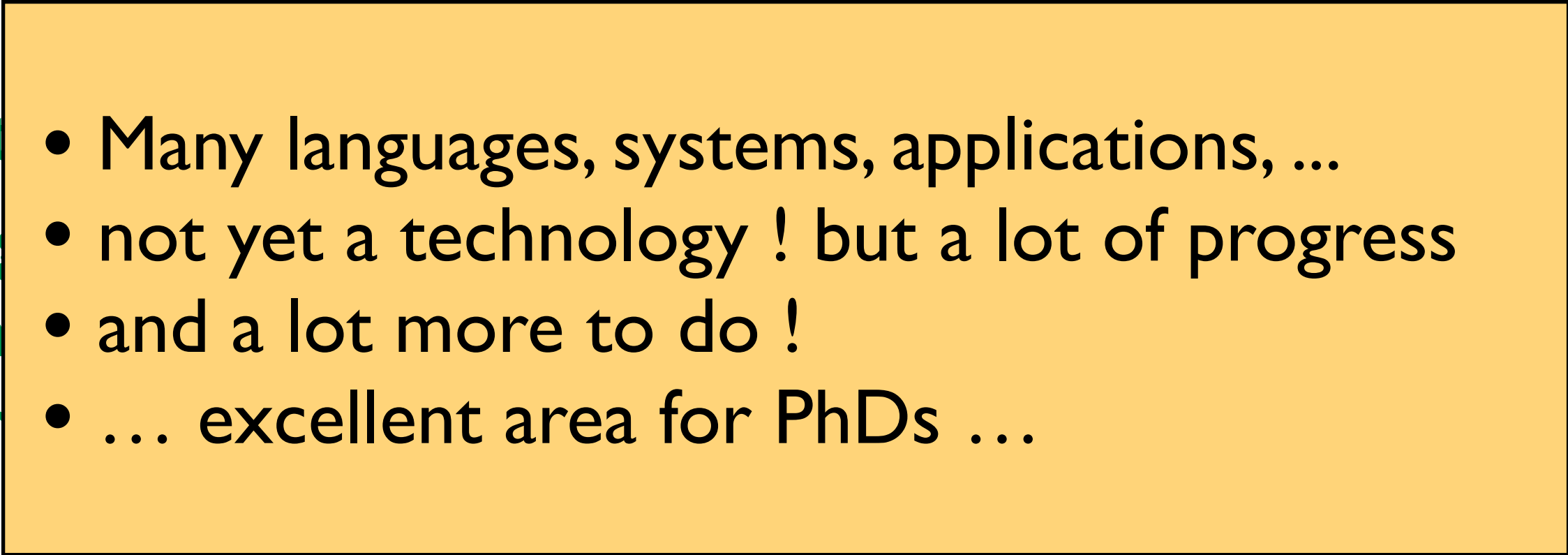


s_t^m

A key question in AI:

Dealing with uncertainty

- probability theory

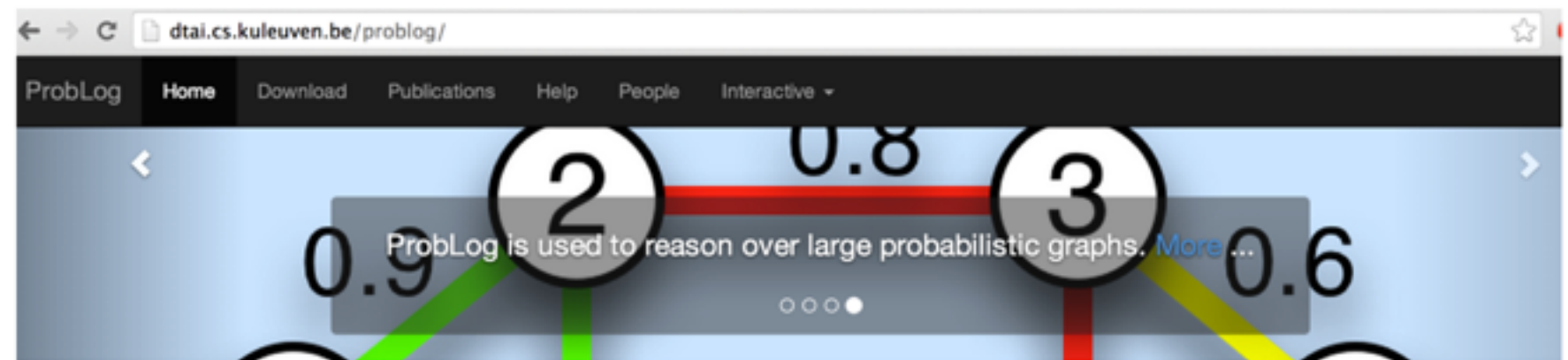
- 
- 
- Many languages, systems, applications, ...
 - not yet a technology ! but a lot of progress
 - and a lot more to do !
 - ... excellent area for PhDs ...

Statistical relational learning
Probabilistic programming, ...

Maurice Bruynooghe
Bart Demoen
Anton Dries
Daan Fierens
Jason Filippou
Bernd Gutmann
Manfred Jaeger
Gerda Janssens
Kristian Kersting
Angelika Kimmig
Theofrastos Mantadelis
Wannes Meert
Bogdan Moldovan
Siegfried Nijssen
Davide Nitti
Joris Renkens
Kate Revoredo
Ricardo Rocha
Vitor Santos Costa
Dimitar Shterionov
Ingo Thon
Hannu Toivonen
Guy Van den Broeck
Mathias Verbeke
Jonas Vlasselaer

Thanks !

<http://dtai.cs.kuleuven.be/problog>



Introduction.

Probabilistic logic programs are logic programs in which some of the facts are annotated with probabilities.

ProbLog is a tool that allows you to intuitively build programs that do not only encode **complex interactions** between a large sets of **heterogenous components** but also the inherent **uncertainties** that are present in real-life situations.

The engine tackles several tasks such as computing the marginals given evidence and learning from (partial) interpretations. ProbLog is a suite of efficient algorithms for various inference tasks. It is based on a conversion of the program and the queries and evidence to a weighted Boolean formula. This allows us to reduce the inference tasks to well-studied tasks such as weighted model counting, which can be solved using state-of-the-art methods known from the graphical model and knowledge compilation literature.

The Language. Probabilistic Logic Programming.

ProbLog makes it easy to express complex, probabilistic models.

```
0.3::stress(X) :- person(X).  
0.2::influences(X,Y) :- person(X), person(Y).
```